



**Sizes** 22 .. 52



Weight 0.77 kg .. 8.05 kg



**Gripping force** 320 N .. 1760 N

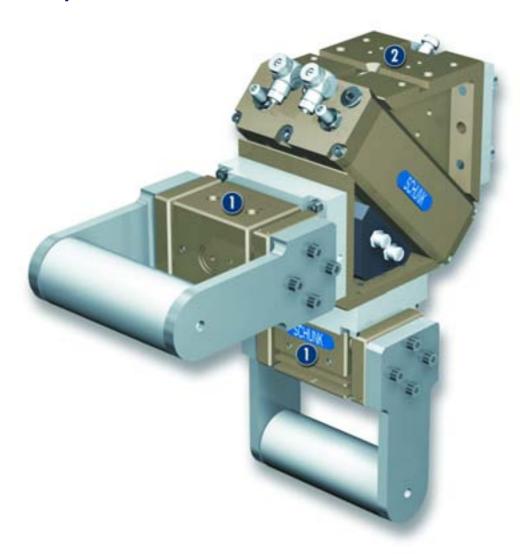


Stroke per finger 14 mm .. 64 mm



Workpiece weight 1.60 kg .. 8.80 kg

### **Application example**



Rapid loading and unloading unit on a swivel head base. Due to the sturdiness of this unit, it is particularly suitable for use in machine tools.

PSH 22-2 2-Finger Parallel Gripper



PSK 34 Swivel Head

# **PSH**

# **Long-stroke Gripper**

2-Finger parallel gripper with long jaw stroke and dirt-resistant round guides

### **Area of application**

for slightly dirty working environments and a broad range of parts

# Your advantages and benefits

**High maximum load capabilities possible** suitable for the use of long gripper fingers

**Dirt-protected round guides** sealed, for long strokes

**Attached to two gripper sides with centering** for universal and flexible gripper mounting

Air supply via hose-free direct connection or screw connections

for the flexible supply of compressed air in all automation systems

Comprehensive sensor accessories

for diverse monitoring tasks and stroke position monitoring



#### General information on the series

#### Working principle

Pneumatic double piston system synchronized by rack and pinion principle

#### **Housing material**

Aluminum alloy, hard-anodized

#### Base jaw material

Aluminum alloy, hard-anodized

#### **Actuation**

Pneumatic, with filtered compressed air (10  $\mu$ m): Dry, lubricated or non-lubricated Pressure medium: Requirements on quality of the compressed air according to DIN ISO 8573-1: 6 4 4.

#### Warranty

24 months

#### Scope of delivery

Centering sleeves, O-rings for direct connection, assembly and operating manual with manufacturer's declaration

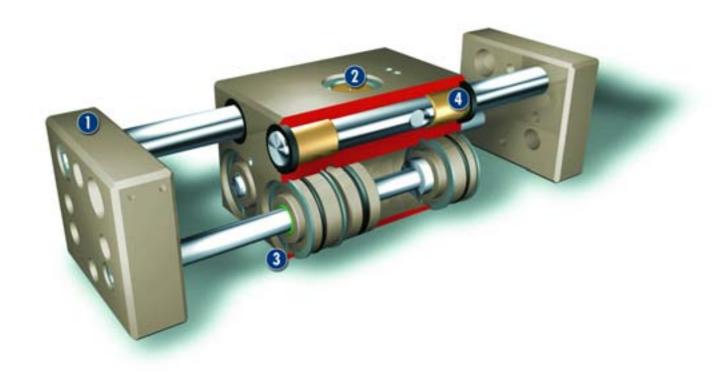
#### Maintenance of gripping force

Possible with SDV-P pressure maintenance valve





### **Sectional diagram**



- Base jaw
  for the connection of workpiece-specific
  gripper fingers
- Kinematics
  rack and pinion principle for centric gripping
- Housing

  weight-reduced through the use of a hardanodized, high-strength aluminum alloy
- Round guides sealed, for long strokes

### **Function description**

The application of pressure on the pistons sets the base jaws, each of which is secured to the piston and the rack, in motion. The jaw stroke is synchronized by means of rack and pinion kinematics.

### **Options and special information**

#### **Finger position**

can be monitored by magnetic and/or inductive proximity switches. Unsynchronized version available on request as a special design.



#### **Accessories**



**Centering sleeves** 



**Fittings** 



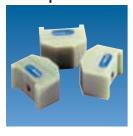
**MMS** magnetic switches



IN inductive proximity switches



#### **Quentes plastic inserts**



**HKI** gripper pads



SDV-P pressure maintenance valves



KV/KA sensor cables



V sensor distributors



FPS flexible position sensor



• For the exact size of the required accessories, availability of this size and the designation and ID, please refer to the additional views at the end of the size in question.

You will find more detailed information on our accessory range in the "Accessories" catalog section.

#### General information on the series

#### **Gripping force**

is the arithmetic total of the gripping force applied to each base jaw at distance P (see illustration), measured from the upper edge of the gripper.

#### Finger length

is measured from the upper edge of the gripper housing in the direction of the main

#### Repeat accuracy

is defined as the spread of the limit position after 100 consecutive strokes.

#### Workpiece weight

The recommended workpiece weight is calculated for a force-type connection with a coefficient of friction of 0.1 and a safety factor of 2 against slippage of the workpiece on acceleration due to gravity g. Considerably heavier workpiece weights are permitted with form-fit gripping.

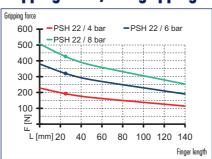
### **Closing and opening times**

Closing and opening times are purely the times that the base jaws or fingers are in motion. Valve switching times, hose filling times or PLC reaction times are not included in the above times and must be taken into consideration when determining cycle times.

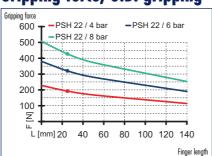




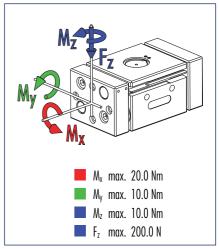
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping

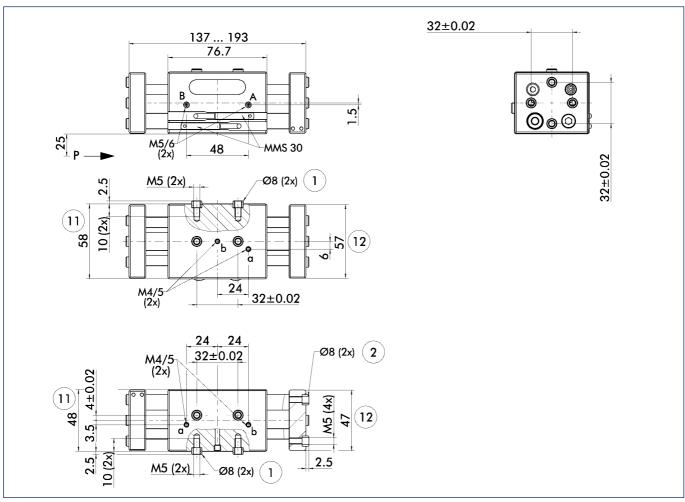


### **Finger load**



Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		PSH 22-1	PSH 22-2	
	ID	0302122	0302123	
Stroke per finger	[mm]	28.0	14.0	
Closing force	[N]	320.0	320.0	
Opening force	[N]	320.0	320.0	
Weight	[kg]	0.95	0.77	
Recommended workpiece weight	[kg]	1.6	1.6	
Air consumption per double stroke	[cm³]	36.0	18.0	
Nominal pressure	[bar]	6.0	6.0	
Minimum pressure	[bar]	3.0	3.0	
Maximum pressure	[bar]	8.0	8.0	
Closing time	[s]	0.1	0.08	
Opening time	[s]	0.1	0.08	
Max. permitted finger length	[mm]	140.0	140.0	
Max. permitted weight per finger	[kg]	0.8	0.8	
IP class		67	67	
Min. ambient temperature	[°C]	-10.0	-10.0	
Max. ambient temperature	[°C]	90.0	90.0	
Repeat accuracy	[mm]	0.1	0.1	

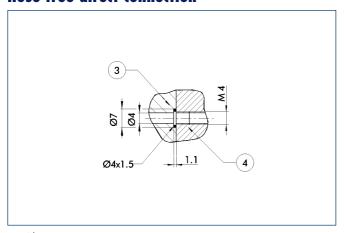


The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- ① The SDV-P pressure maintenance valve can be used as a gripping force safety device (see "Accessories" catalog section).
- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- 1 Gripper connection
  2 Finger connection
  11 Housing

- Jaw

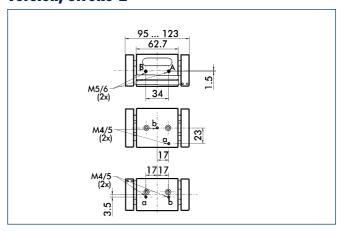
### **Hose-free direct connection**



- 3 Adapter

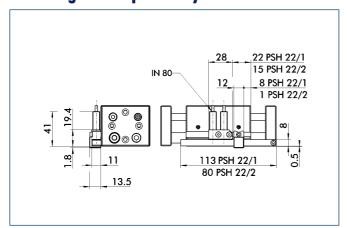
The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

### Version, stroke 2





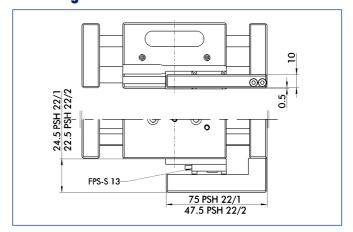
# Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

Description	ID	
HG-PSH 22-1	0300754	
HG-PSH 22-2	0300755	

### **Mounting kit for FPS**

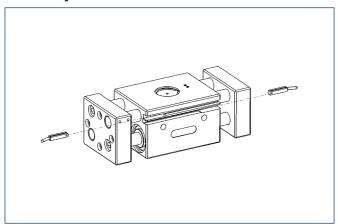


The FPS flexible position sensor can distinguish between five freely programmable ranges or switching points for the stroke of a gripper and can be used in conjunction with a PC as a measuring system.

Description	ID	
AS-PSH 22-1	0301736	
AS-PSH 22-2	0301737	



### **Sensor system**

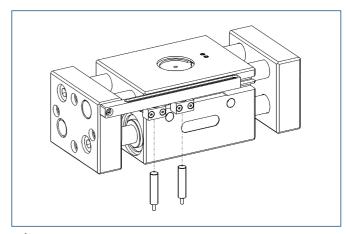




Electronic magnetic switches, for mounting in C-slot

Description	ID	Recommended product	
MMS 30-S-M12-PNP	0301571		
MMS 30-S-M8-PNP	0301471	•	
MMSK 30-S-PNP	0301563		

① Two sensors (NO contacts) are required for each gripper, plus extension cables as an

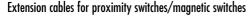


End position monitoring:

Inductive proximity switches, mounted with mounting kit

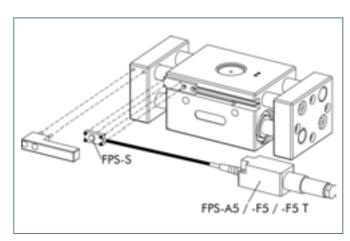
Description	ID	Recommended product
HG-PSH 22-1	0300754	
HG-PSH 22-2	0300755	
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	•
IN-C 80-S-M8	0301475	
INK 80-S	0301550	
INK 80-SL	0301579	

① Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.



Description	ID	
KA BG08-L 3P-0300-PNP	0301622	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

① Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



Measuring system:

FPS Flexible position sensor

Description	ID	
AS-PSH 22-1	0301736	
AS-PSH 22-2	0301737	
FPS-F5	0301805	
FPS-F5 T	0301807	
FPS-S 13	0301705	

① When using an FPS system, an FPS sensor (FPS-S) and an control unit (FPS-F5 / F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as options in the "Accessories" catalog section.



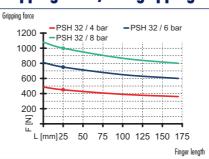
You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

www.schunk.com

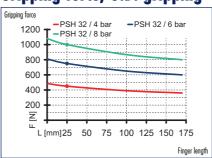




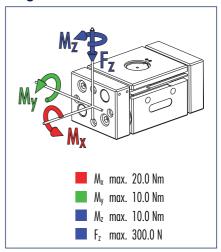
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping

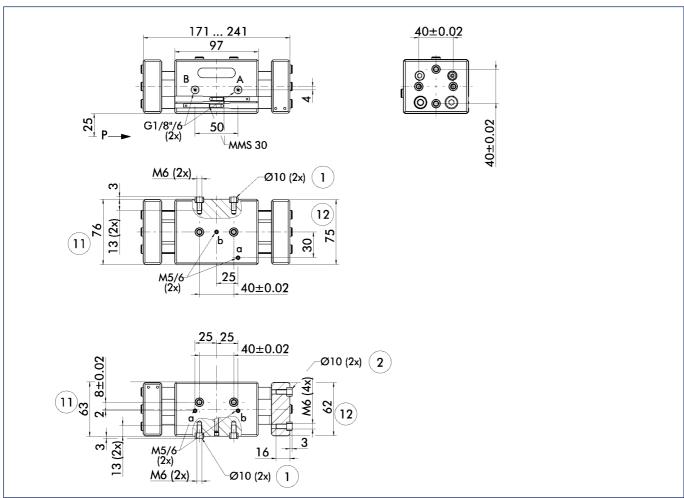


### **Finger load**



Moments and forces apply per base jaw and may occur simultaneously. M<sub>V</sub> may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		PSH 32-1	PSH 32-2	
	ID	0302132	0302133	
Stroke per finger	[mm]	35.0	22.5	
Closing force	[N]	750.0	750.0	
Opening force	[N]	750.0	750.0	
Weight	[kg]	2.05	1.8	
Recommended workpiece weight	[kg]	3.75	3.75	
Air consumption per double stroke	[cm <sup>3</sup> ]	101.0	65.0	
Nominal pressure	[bar]	6.0	6.0	
Minimum pressure	[bar]	3.0	3.0	
Maximum pressure	[bar]	8.0	8.0	
Closing time	[5]	0.2	0.12	
Opening time	[5]	0.2	0.12	
Max. permitted finger length	[mm]	170.0	170.0	
Max. permitted weight per finger	[kg]	1.5	1.5	
IP class		67	67	
Min. ambient temperature	[°C]	-10.0	-10.0	
Max. ambient temperature	[°C]	90.0	90.0	
Repeat accuracy	[mm]	0.1	0.1	

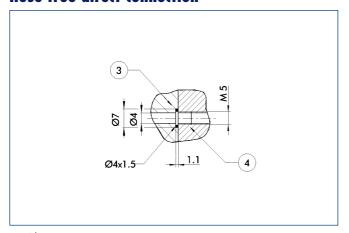


The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- ① The SDV-P pressure maintenance valve can be used as a gripping force safety device (see "Accessories" catalog section).
- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- 1 Gripper connection
  2 Finger connection
  11 Housing

- Jaw

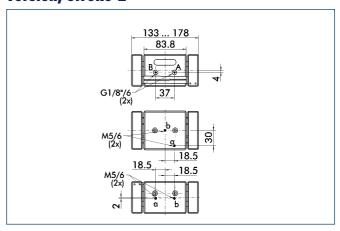
### **Hose-free direct connection**



- 3 Adapter
- (4) Gripper

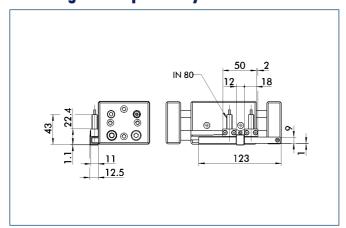
The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

### Version, stroke 2





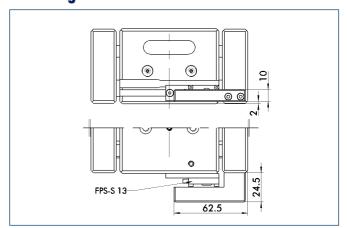
# Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

Description	ID .	
HG-PSH 32	0300756	

### **Mounting kit for FPS**

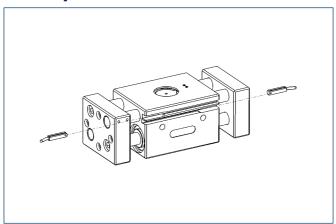


The FPS flexible position sensor can distinguish between five freely programmable ranges or switching points for the stroke of a gripper and can be used in conjunction with a PC as a measuring system.

Description	ID	
AS-PSH 32-2	0301738	



### **Sensor system**

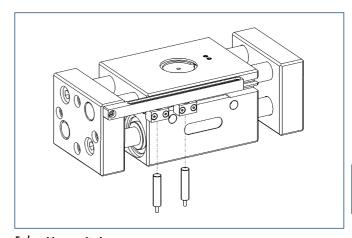


**End position monitoring:** 

Electronic magnetic switches, for mounting in C-slot

Description	ID	Recommended product	
MMS 30-S-M12-PNP	0301571		
MMS 30-S-M8-PNP	0301471	•	
MMSK 30-S-PNP	0301563		

① Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.



End position monitoring:

Inductive proximity switches, mounted with mounting kit

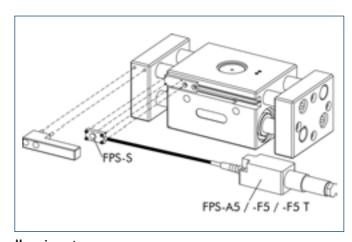
Description .	, ID	Recommended product
HG-PSH 32	0300756	
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	•
IN-C 80-S-M8	0301475	
INK 80-S	0301550	
INK 80-SL	0301579	

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

Extension cables for proximity switches/magnetic switches

Description	ID	
KA BG08-L 3P-0300-PNP	0301622	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



Measuring system:

FPS Flexible position sensor

TI S TIOMISIO POSITIOI	. 5011501	
Description	ID	
AS-PSH 32-2	0301738	
FPS-F5	0301805	
FPS-F5 T	0301807	
FPS-S 13	0301705	

(i) When using an FPS system, an FPS sensor (FPS-S) and an control unit (FPS-F5 / F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as options in the "Accessories" catalog section.

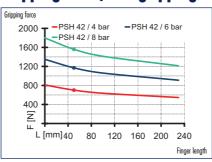


You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

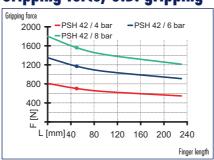




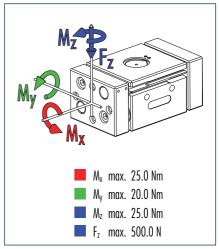
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping

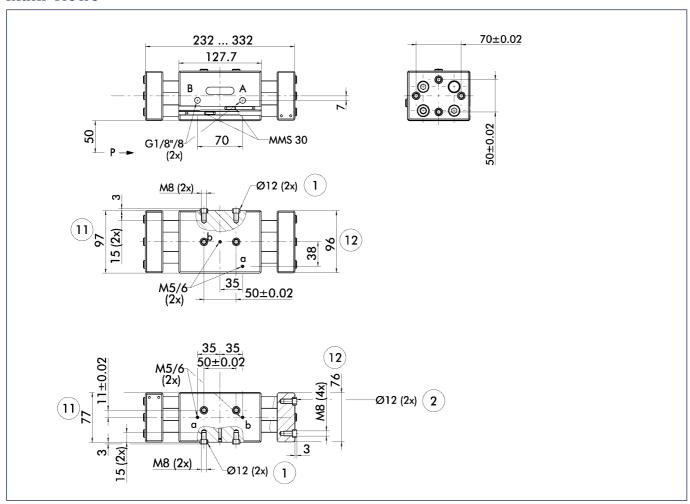


# **Finger load**



Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		PSH 42-1	PSH 42-2	
	ID	0302142	0302143	
Stroke per finger	[mm]	50.0	29.0	
Closing force	[N]	1170.0	1170.0	
Opening force	[N]	1170.0	1170.0	
Weight	[kg]	4.65	3.9	
Recommended workpiece weight	[kg]	4.25	4.25	
Air consumption per double stroke	[cm <sup>3</sup> ]	255.0	148.0	
Nominal pressure	[bar]	6.0	6.0	
Minimum pressure	[bar]	3.0	3.0	
Maximum pressure	[bar]	8.0	8.0	
Closing time	[s]	0.25	0.15	
Opening time	[s]	0.25	0.15	
Max. permitted finger length	[mm]	230.0	230.0	
Max. permitted weight per finger	[kg]	2.5	2.5	
IP class		67	67	
Min. ambient temperature	[°(]	-10.0	-10.0	
Max. ambient temperature	[° <b>(</b> ]	90.0	90.0	
Repeat accuracy	[mm]	0.05	0.05	

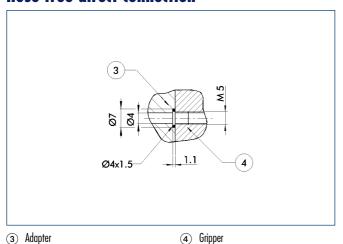


The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- ① The SDV-P pressure maintenance valve can be used as a gripping force safety device (see "Accessories" catalog section).
- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- 1 Gripper connection
  2 Finger connection
  11 Housing

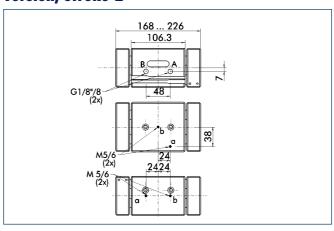
- Jaw

### **Hose-free direct connection**



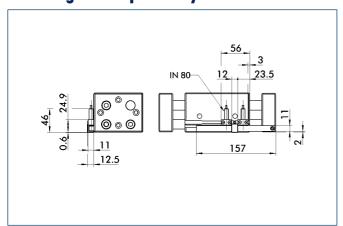
The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

### Version, stroke 2





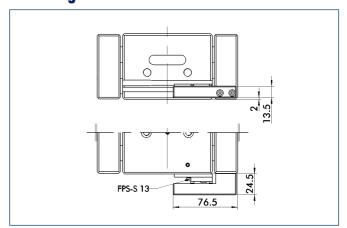
# Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

Description	ID	
HG-PSH 42	0300757	

# **Mounting kit for FPS**

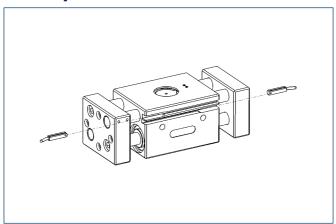


The FPS flexible position sensor can distinguish between five freely programmable ranges or switching points for the stroke of a gripper and can be used in conjunction with a PC as a measuring system.

Description	ID	
AS-PSH 42-2	0301739	



### **Sensor system**

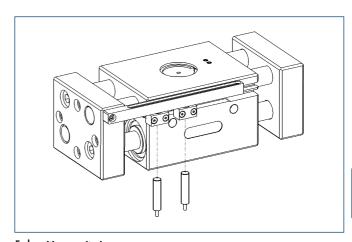


**End position monitoring:** 

Electronic magnetic switches, for mounting in C-slot

Description	ID	Recommended product
MMS 30-S-M12-PNP	0301571	
MMS 30-S-M8-PNP	0301471	•
MMSK 30-S-PNP	0301563	

① Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

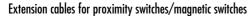


End position monitoring:

Inductive proximity switches, mounted with mounting kit

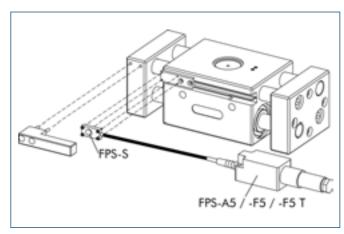
Description	· ID	Recommended product	
HG-PSH 42	0300757		
IN 80-S-M12	0301578		
IN 80-S-M8	0301478	•	
IN-C 80-S-M8	0301475		
INK 80-S	0301550		
INK 80-SL	0301579		

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.



Description	ID	
KA BG08-L 3P-0300-PNP	0301622	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



Measuring system:

FPS Flexible position sensor

TI S TIOMISIO POSITIOI	. 5011501	
Description	ID	
AS-PSH 42-2	0301739	
FPS-F5	0301805	
FPS-F5 T	0301807	
FPS-S 13	0301705	

(i) When using an FPS system, an FPS sensor (FPS-S) and an control unit (FPS-F5 / F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as options in the "Accessories" catalog section.

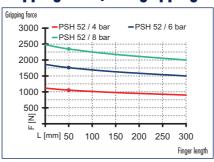


You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

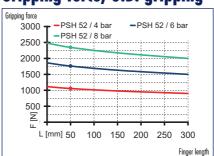




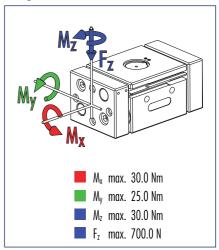
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping

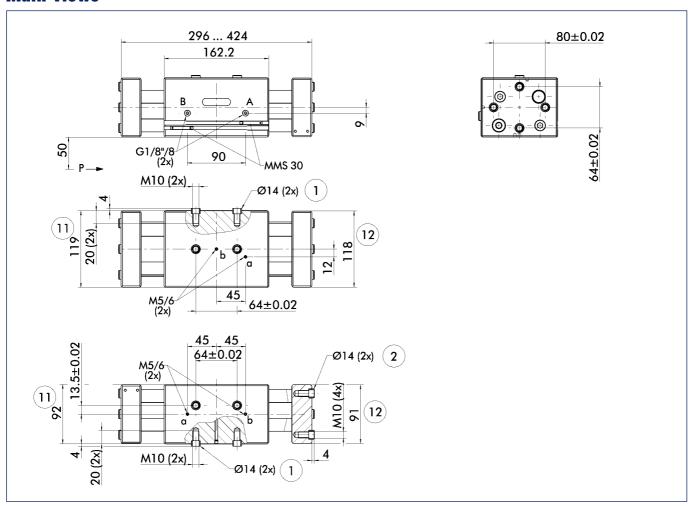


### **Finger load**



Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

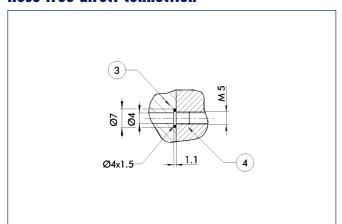
Description		PSH 52	
	ID	0302152	
Stroke per finger	[mm]	64.0	
Closing force	[N]	1760.0	
Opening force	[N]	1760.0	
Weight	[kg]	8.05	
Recommended workpiece weight	[kg]	8.8	
Air consumption per double stroke	[cm³]	504.0	
Nominal pressure	[bar]	6.0	
Minimum pressure	[bar]	3.0	
Maximum pressure	[bar]	8.0	
Closing time	[5]	0.4	
Opening time	[5]	0.4	
Max. permitted finger length	[mm]	300.0	
Max. permitted weight per finger	[kg]	3.5	
IP class		67	
Min. ambient temperature	[°C]	-10.0	
Max. ambient temperature	[°C]	90.0	
Repeat accuracy	[mm]	0.05	



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- ① The SDV-P pressure maintenance valve can be used as a gripping force safety device (see "Accessories" catalog section).
- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- finger connectionFinger connection
- 11 Housing
- (12) Jaw

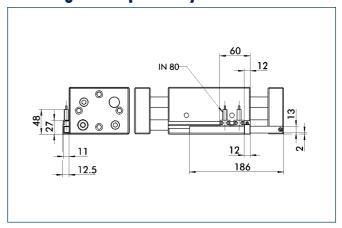
#### **Hose-free direct connection**



- 3 Adapter

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

# Mounting kit for proximity switch

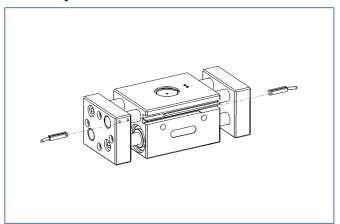


The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

Description	ID	
HG-PSH 52	0300759	



### **Sensor system**

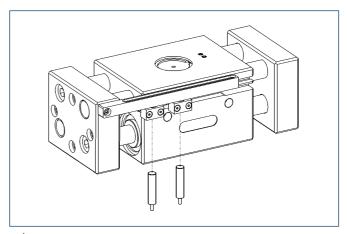


End position monitoring:

Electronic magnetic switches, for mounting in C-slot

Description	ID	Recommended product
MMS 30-S-M12-PNP	0301571	
MMS 30-S-M8-PNP	0301471	•
MMSK 30-S-PNP	0301563	

① Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.



End position monitoring:

Inductive proximity switches, mounted with mounting kit

Description	ID	Recommended product	
HG-PSH 52	0300759		
IN 80-S-M12	0301578		
IN 80-S-M8	0301478	•	
IN-C 80-S-M8	0301475		
INK 80-S	0301550		
INK 80-SL	0301579		

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

Extension cables for proximity switches/magnetic switches

Description	ID	
KA BG08-L 3P-0300-PNP	0301622	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

