Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



Sizes 60...280



Weight 0.085 kg .. 4.2 kg



Gripping force 45 N .. 540 N

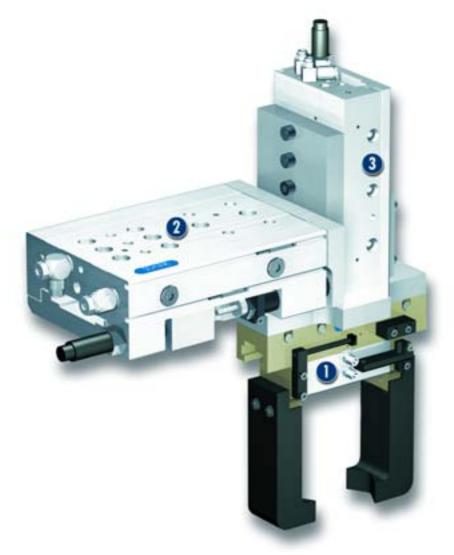


Stroke per finger 10 mm .. 60 mm



Workpiece weight 0.3 kg .. 2.7 kg

Application example



Ejection unit for small components, which require an especially long gripper stroke due to their great variation in size



KGG 140 2-Finger Parallel Gripper with workpiece-specific fingers



FST-S 25-40 Mini-slide for horizontal movement

3





Gripper for Small Components

Narrow 2-finger parallel gripper with long stroke

Area of application

for universal use in clean environments with light to medium workpiece weights and a long stroke range

Your advantages and benefits

Robust T-slot guide for high maximum moments

Pneumatic 2-piston drive design for direct power transmission and high efficiency

Rack and pinion principle for centric clamping, even with long strokes

Mounting from two sides in three screw directions for universal and flexible gripper assembly

Air supply via hose-free direct connection or screw connections

for the flexible supply of compressed air in all automation systems



General information on the series

Working principle Directly driven base jaws, synchronized by rack and pinion

Housing material Aluminum alloy, hard-anodized

Base jaw material Aluminum alloy, hard-anodized

Actuation

Pneumatic, with filtered compressed air (10 μ m): Dry, lubricated or non-lubricated Pressure medium: Requirements on quality of the compressed air according to DIN ISO 8573-1: 6 4 4.

Warranty

24 months

Scope of delivery Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly and operating manual with manufacturer's declaration

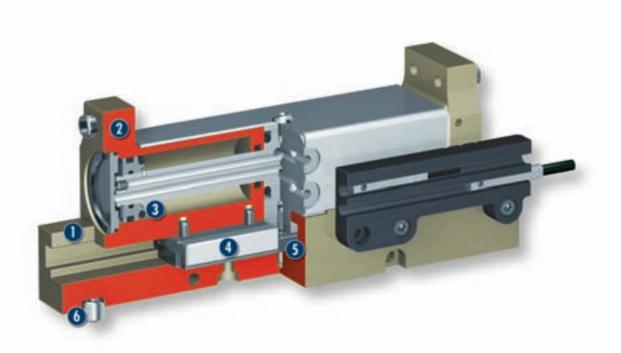
Maintenance of gripping force

possible with SDV-P pressure maintenance valve



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Sectional diagram



1 Housing

weight-reduced through the use of a hardanodized, high-strength aluminum alloy



Base jaws

for the connection of workpiece-specific gripper fingers



Drive Pneumatic 2-piston system



Guidance high maximum moments through robust T-slot guide



Kinematics

rack and pinion principle for centric gripping, even with long strokes



Centering and mounting possibilities for assembly of the gripper to a base area and at the long side

Function description

The base jaws, arranged in a line, are introduced with compressed air directly by the fixed piston, which causes them to open and close. The base jaws are synchronized by the internal rack and pinion arrangement.

Options and special information

Please note that the mass moment of inertia of the gripper fingers must be kept to a minimum in the case of long-stroke grippers.



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SCHUNK

Accessories

Accessories from SCHUNK – the suitable supplement for maximum functionality, reliability and performance of all automation modules.

HM carbide clamping inserts



Quentes plastic inserts





IN inductive proximity switches



KV/KA sensor cables







FPS flexible position sensor



HKI gripper pads



SDV-P pressure maintenance valves



Finger blanks



For the exact size of the required accessories, availability of this size and the designation and ID, please refer to the additional views at the end of the size in question. You will find more detailed information on our accessory range in the "Accessories" catalog section.

General information on the series

Gripping force

is the arithmetic total of the gripping force applied to each base jaw at distance P (see illustration), measured from the upper edge of the gripper.

Finger length

is measured from the upper edge of the gripper housing in the direction of the main axis.

Repeat accuracy

is defined as the spread of the limit position after 100 consecutive strokes.

Workpiece weight

The recommended workpiece weight is calculated for a force-type connection with a coefficient of friction of 0.1 and a safety factor of 2 against slippage of the workpiece on acceleration due to gravity g. Considerably heavier workpiece weights are permitted with form-fit gripping.

Closing and opening times

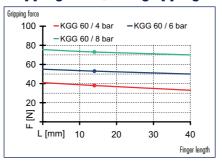
Closing and opening times are purely the times that the base jaws or fingers are in motion. Valve switching times, hose filling times or PLC reaction times are not included in the above times and must be taken into consideration when determining cycle times.



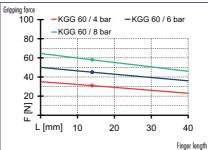
Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



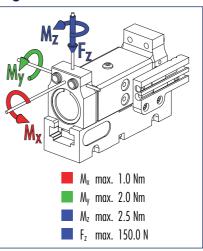
Gripping force, I.D. gripping



Gripping force, O.D. gripping



Finger load



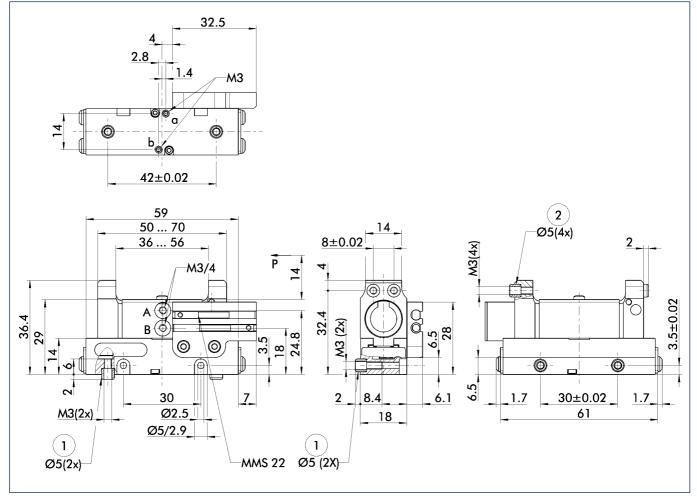
(1) Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

| Description | | KGG 60-20 | KGG 60-40 | |
|-----------------------------------|--------------------|-----------|-----------|--|
| | ID | 0303050 | 0303051 | |
| Stroke per finger | [mm] | 10.0 | 20.0 | |
| Closing force | [N] | 45.0 | 45.0 | |
| Opening force | [N] | 53.0 | 53.0 | |
| Weight | [kg] | 0.085 | 0.108 | |
| Recommended workpiece weight | [kg] | 0.23 | 0.23 | |
| Air consumption per double stroke | [cm ³] | 3.0 | 6.0 | |
| Nominal pressure | [bar] | 6.0 | 6.0 | |
| Minimum pressure | [bar] | 2.0 | 2.0 | |
| Maximum pressure | [bar] | 8.0 | 8.0 | |
| Closing time | [5] | 0.03 | 0.04 | |
| Opening time | [S] | 0.03 | 0.04 | |
| Max. permitted finger length | [mm] | 42.0 | 42.0 | |
| Max. permitted weight per finger | [kg] | 0.04 | 0.04 | |
| IP class | | 40 | 40 | |
| Min. ambient temperature | [° (] | -10.0 | -10.0 | |
| Max. ambient temperature | [° (] | 90.0 | 90.0 | |
| Repeat accuracy | [mm] | 0.02 | 0.02 | |



Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

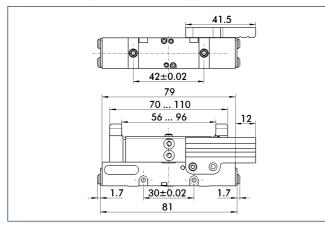
Main views



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(1) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

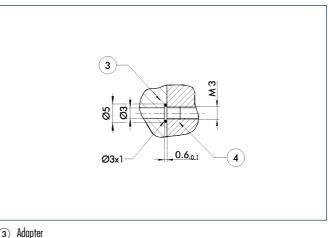
KGG 60-40 (double stroke)



The KGG 60-40 is a version with double stroke length.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- ① Gripper connection
- 2 Finger connection

Hose-free direct connection



3

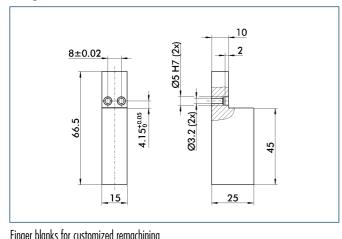
(ā) Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.



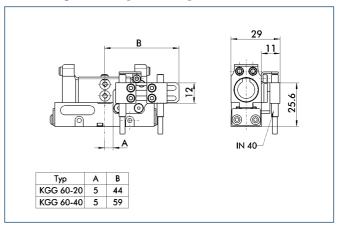
Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

Finger blanks



| Description | Material | Scope of delivery | ID |
|-------------|----------|-------------------|---------|
| RB 60 | Aluminum | 2 | 0303087 |

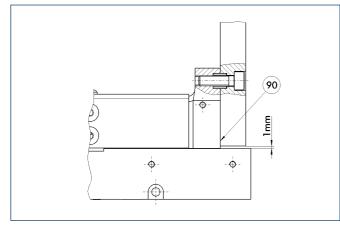
Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

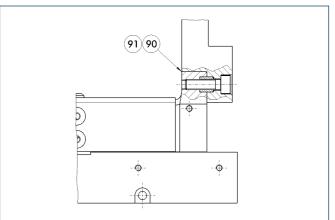
| Description | ID ' | , |
|----------------------|---------|---|
| AS-KGG 60-20 / 70-24 | 0303081 | |
| AS-KGG 60-40 / 70-48 | 0303080 | |

Jaw design O.D. gripping



90 Support top jaws at the base jaw

Jaw design I.D. gripping

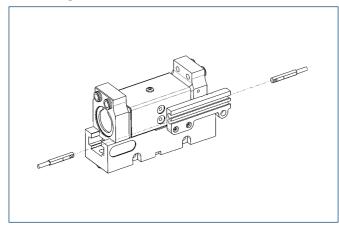


90 Support top jaws at the base jaw

(91) For dimensions of steps at the top jaw see drawings of finger blanks



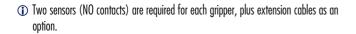
Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

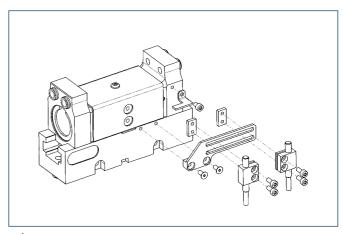
| Description | ID | Recommended product | |
|--------------------|---------|---------------------|--|
| MMS 22-S-M5-NPN | 0301439 | · | |
| MMS 22-S-M5-NPN-SA | 0301449 | | |
| MMS 22-S-M5-PNP | 0301438 | | |
| MMS 22-S-M5-PNP-SA | 0301448 | | |
| MMS 22-S-M8-NPN | 0301433 | | |
| MMS 22-S-M8-NPN-SA | 0301443 | | |
| MMS 22-S-M8-PNP | 0301432 | • | |
| MMS 22-S-M8-PNP-SA | 0301442 | | |
| MMSK 22-S-NPN | 0301435 | | |
| MMSK 22-S-NPN-SA | 0301445 | | |
| MMSK 22-S-PNP | 0301434 | | |
| MMSK 22-S-PNP-SA | 0301444 | | |



Extension cables for proximity switches/magnetic switches

| Description | ID | |
|--------------------------|---------|--|
| KA BG05-L 3P-0300 | 0301652 | |
| KA BGO8-L 3P-0300-PNP | 0301622 | |
| KA BW05-L 3P-0300 | 0301650 | |
| KA BWO8-L 3P-0300-NPN | 0301602 | |
| KA BWO8-L 3P-0300-PNP | 0301594 | |
| KA BW08-L 3P-0500-NPN | 9641116 | |
| KA BW08-L 3P-0500-PNP | 0301502 | |
| KA BW12-L 3P-0300-PNP | 0301503 | |
| KA BW12-L 3P-0500-PNP | 0301507 | |
| KV BW08-SG08 3P-0030-PNP | 0301495 | |
| KV BW08-SG08 3P-0100-PNP | 0301496 | |
| KV BW08-SG08 3P-0200-PNP | 0301497 | |
| KV BW12-SG12 3P-0030-PNP | 0301595 | |
| KV BW12-SG12 3P-0100-PNP | 0301596 | |
| KV BW12-SG12 3P-0200-PNP | 0301597 | |
| | | |

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



End position monitoring:

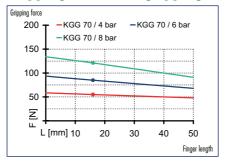
| Inductive proximity switches, mounted with mounting kit | | | |
|---|---------|--|--|
| Description | ID | | |
| AS-KGG 60-20 / 70-24 | 0303081 | | |
| AS-KGG 60-40 / 70-48 | 0303080 | | |
| IN 40-S-M12 | 0301574 | | |
| IN 40-S-M8 | 0301474 | | |
| INK 40-S | 0301555 | | |

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

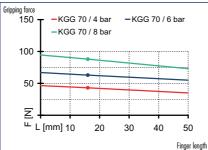
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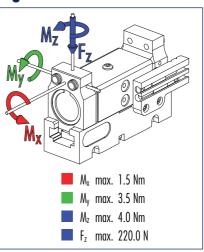
Gripping force, I.D. gripping



Gripping force, O.D. gripping



Finger load



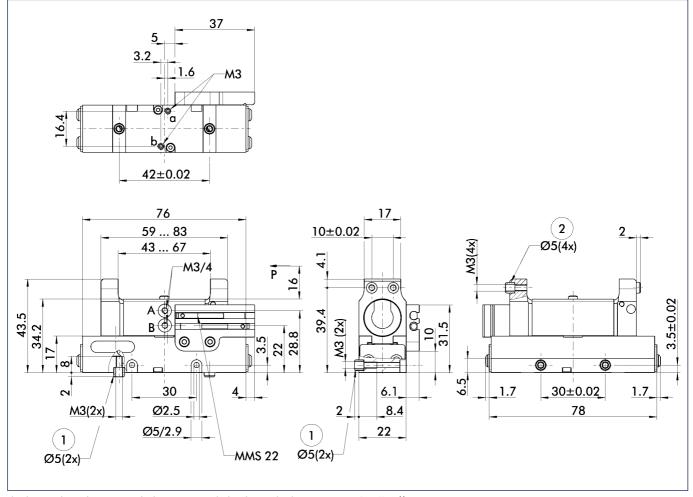
① Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

| Description | | KGG 70-24 | KGG 70-48 | |
|-----------------------------------|--------------------|-----------|-----------|--|
| | ID | 0303055 | 0303056 | |
| Stroke per finger | [mm] | 12.0 | 24.0 | |
| Closing force | [N] | 62.0 | 62.0 | |
| Opening force | [N] | 85.0 | 85.0 | |
| Weight | [kg] | 0.15 | 0.192 | |
| Recommended workpiece weight | [kg] | 0.32 | 0.32 | |
| Air consumption per double stroke | [cm ³] | 5.0 | 10.0 | |
| Nominal pressure | [bar] | 6.0 | 6.0 | |
| Minimum pressure | [bar] | 2.0 | 2.0 | |
| Maximum pressure | [bar] | 8.0 | 8.0 | |
| Closing time | [5] | 0.04 | 0.05 | |
| Opening time | [5] | 0.04 | 0.05 | |
| Max. permitted finger length | [mm] | 50.0 | 50.0 | |
| Max. permitted weight per finger | [kg] | 0.06 | 0.06 | |
| IP class | | 40 | 40 | |
| Min. ambient temperature | [° (] | -10.0 | -10.0 | |
| Max. ambient temperature | [° (] | 90.0 | 90.0 | |
| Repeat accuracy | [mm] | 0.02 | 0.02 | |



Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

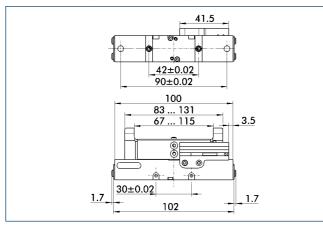
Main views



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(1) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

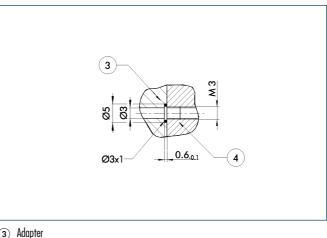
KGG 70-48 (double stroke)



The KGG 70-48 is a version with double stroke length.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- ① Gripper connection
- 2 Finger connection

Hose-free direct connection



3

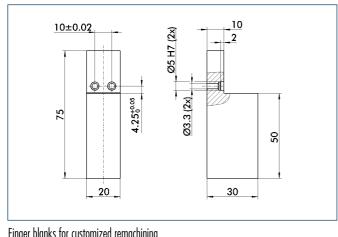
(ā) Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.



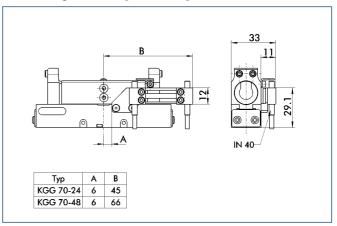
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Finger blanks



| Description | Material | Scope of delivery | ID |
|-------------|----------|-------------------|---------|
| RB 70 | Aluminum | 2 | 0303088 |

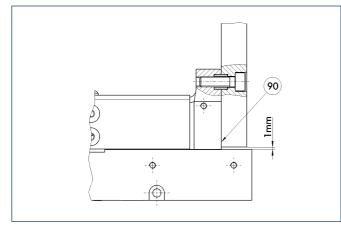
Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

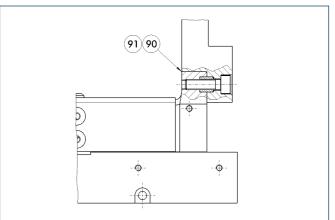
| Description | ID . | 1 |
|----------------------|---------|---|
| AS-KGG 60-20 / 70-24 | 0303081 | |
| AS-KGG 60-40 / 70-48 | 0303080 | |

Jaw design O.D. gripping



90 Support top jaws at the base jaw

Jaw design I.D. gripping

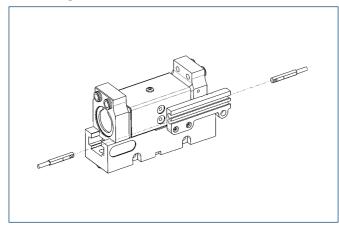


90 Support top jaws at the base jaw

(91) For dimensions of steps at the top jaw see drawings of finger blanks



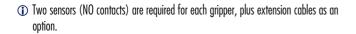
Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

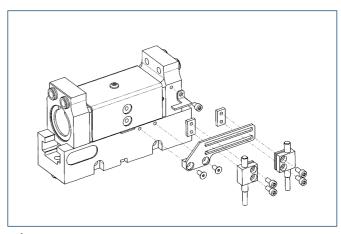
| Description | ID | Recommended product | |
|--------------------|---------|---------------------|--|
| MMS 22-S-M5-NPN | 0301439 | | |
| MMS 22-S-M5-NPN-SA | 0301449 | | |
| MMS 22-S-M5-PNP | 0301438 | | |
| MMS 22-S-M5-PNP-SA | 0301448 | | |
| MMS 22-S-M8-NPN | 0301433 | | |
| MMS 22-S-M8-NPN-SA | 0301443 | | |
| MMS 22-S-M8-PNP | 0301432 | • | |
| MMS 22-S-M8-PNP-SA | 0301442 | | |
| MMSK 22-S-NPN | 0301435 | | |
| MMSK 22-S-NPN-SA | 0301445 | | |
| MMSK 22-S-PNP | 0301434 | | |
| MMSK 22-S-PNP-SA | 0301444 | | |



Extension cables for proximity switches/magnetic switches

| Description | ID | |
|--------------------------|---------|--|
| KA BG05-L 3P-0300 | 0301652 | |
| KA BGO8-L 3P-0300-PNP | 0301622 | |
| KA BW05-L 3P-0300 | 0301650 | |
| KA BWO8-L 3P-0300-NPN | 0301602 | |
| KA BWO8-L 3P-0300-PNP | 0301594 | |
| KA BW08-L 3P-0500-NPN | 9641116 | |
| KA BW08-L 3P-0500-PNP | 0301502 | |
| KA BW12-L 3P-0300-PNP | 0301503 | |
| KA BW12-L 3P-0500-PNP | 0301507 | |
| KV BW08-SG08 3P-0030-PNP | 0301495 | |
| KV BW08-SG08 3P-0100-PNP | 0301496 | |
| KV BW08-SG08 3P-0200-PNP | 0301497 | |
| KV BW12-SG12 3P-0030-PNP | 0301595 | |
| KV BW12-SG12 3P-0100-PNP | 0301596 | |
| KV BW12-SG12 3P-0200-PNP | 0301597 | |
| | | |

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



End position monitoring:

| Inductive proximity switches, mounted with mounting kit | | | |
|---|---------|--|--|
| Description | ID | | |
| AS-KGG 60-20 / 70-24 | 0303081 | | |
| AS-KGG 60-40 / 70-48 | 0303080 | | |
| IN 40-S-M12 | 0301574 | | |
| IN 40-S-M8 | 0301474 | | |
| INK 40-S | 0301555 | | |

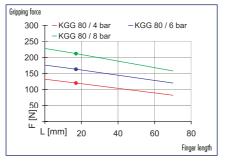
Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.



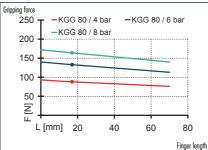
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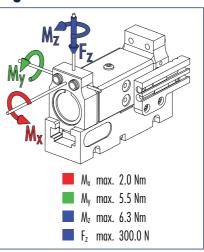
Gripping force, I.D. gripping



Gripping force, O.D. gripping



Finger load



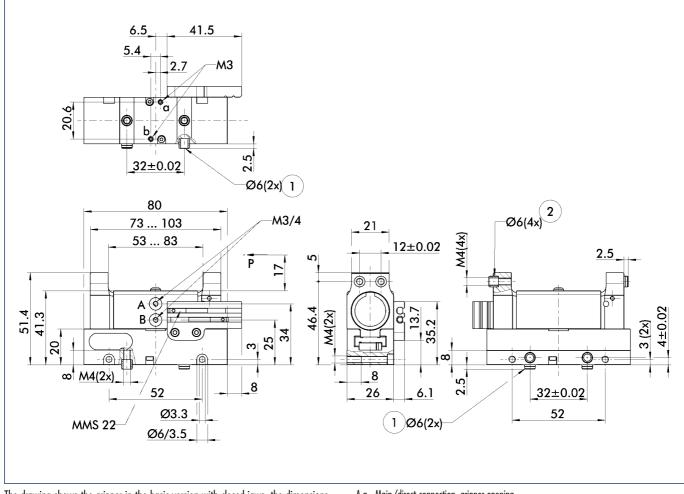
Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

| Description | | KGG 80-30 | KGG 80-60 | |
|-----------------------------------|--------------------|-----------|-----------|--|
| | ID | 0303060 | 0303061 | |
| Stroke per finger | [mm] | 15.0 | 30.0 | |
| Closing force | [N] | 130.0 | 130.0 | |
| Opening force | [N] | 165.0 | 165.0 | |
| Weight | [kg] | 0.25 | 0.33 | |
| Recommended workpiece weight | [kg] | 0.66 | 0.66 | |
| Air consumption per double stroke | [cm ³] | 12.0 | 24.0 | |
| Nominal pressure | [bar] | 6.0 | 6.0 | |
| Minimum pressure | [bar] | 2.0 | 2.0 | |
| Maximum pressure | [bar] | 8.0 | 8.0 | |
| Closing time | [5] | 0.05 | 0.08 | |
| Opening time | [5] | 0.05 | 0.07 | |
| Max. permitted finger length | [mm] | 80.0 | 80.0 | |
| Max. permitted weight per finger | [kg] | 0.15 | 0.15 | |
| IP class | | 40 | 40 | |
| Min. ambient temperature | [° (] | -10.0 | -10.0 | |
| Max. ambient temperature | [° (] | 90.0 | 90.0 | |
| Repeat accuracy | [mm] | 0.02 | 0.02 | |



Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

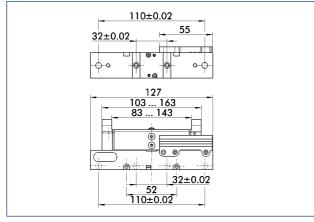
Main views



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(i) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

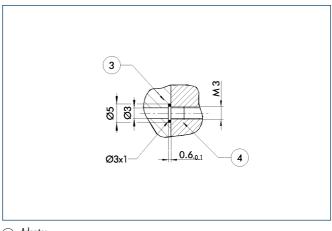
KGG 80-60 (double stroke)



The KGG 80-60 is a version with double stroke length.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- ① Gripper connection
- (2) Finger connection

Hose-free direct connection



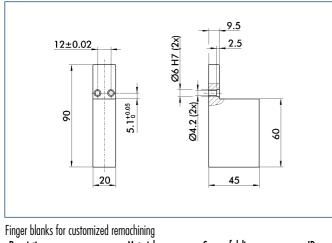
3 Adapter4 Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.



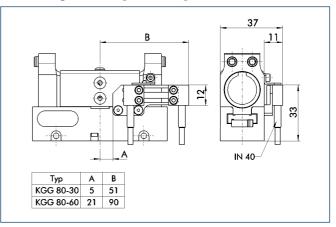
Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

Finger blanks



| Description | Material | Scope of delivery | ID |
|-------------|----------|-------------------|---------|
| RB 80 | Aluminum | 2 | 0303089 |

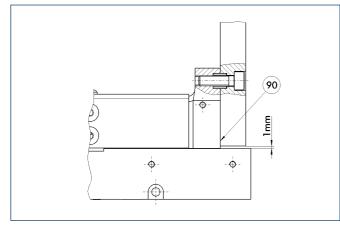
Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

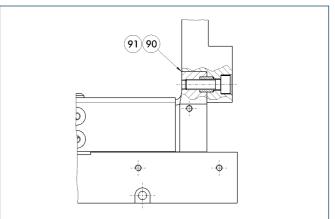
| Description | ID |
|--------------------------------|---------|
| AS-KGG 80-30 | 0303083 |
| AS-KGG 80-60 / 100-80 / 140-60 | 0303084 |

Jaw design O.D. gripping



90 Support top jaws at the base jaw

Jaw design I.D. gripping

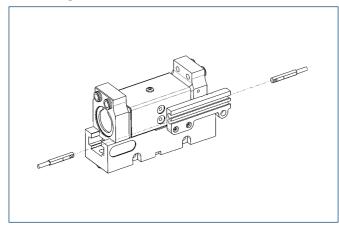


90 Support top jaws at the base jaw

(91) For dimensions of steps at the top jaw see drawings of finger blanks



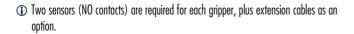
Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

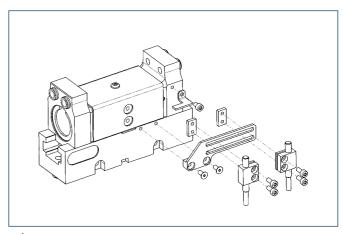
| Description | ID | Recommended product |
|--------------------|---------|---------------------|
| MMS 22-S-M5-NPN | 0301439 | - |
| MMS 22-S-M5-NPN-SA | 0301449 | |
| MMS 22-S-M5-PNP | 0301438 | |
| MMS 22-S-M5-PNP-SA | 0301448 | |
| MMS 22-S-M8-NPN | 0301433 | |
| MMS 22-S-M8-NPN-SA | 0301443 | |
| MMS 22-S-M8-PNP | 0301432 | • |
| MMS 22-S-M8-PNP-SA | 0301442 | |
| MMSK 22-S-NPN | 0301435 | |
| MMSK 22-S-NPN-SA | 0301445 | |
| MMSK 22-S-PNP | 0301434 | |
| MMSK 22-S-PNP-SA | 0301444 | |
| | | |



Extension cables for proximity switches/magnetic switches

| Description | ID | • |
|--------------------------|---------|---|
| KA BG05-L 3P-0300 | 0301652 | |
| KA BGO8-L 3P-0300-PNP | 0301622 | |
| KA BW05-L 3P-0300 | 0301650 | |
| KA BW08-L 3P-0300-NPN | 0301602 | |
| KA BWO8-L 3P-0300-PNP | 0301594 | |
| KA BW08-L 3P-0500-NPN | 9641116 | |
| KA BW08-L 3P-0500-PNP | 0301502 | |
| KA BW12-L 3P-0300-PNP | 0301503 | |
| KA BW12-L 3P-0500-PNP | 0301507 | |
| KV BW08-SG08 3P-0030-PNP | 0301495 | |
| KV BW08-SG08 3P-0100-PNP | 0301496 | |
| KV BW08-SG08 3P-0200-PNP | 0301497 | |
| KV BW12-SG12 3P-0030-PNP | 0301595 | |
| KV BW12-SG12 3P-0100-PNP | 0301596 | |
| KV BW12-SG12 3P-0200-PNP | 0301597 | |

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



End position monitoring:

Inductive proximity switches, mounted with mounting kit

| Description | ĬD | |
|--------------------------------|---------|--|
| AS-KGG 80-30 | 0303083 | |
| AS-KGG 80-60 / 100-80 / 140-60 | 0303084 | |
| IN 40-S-M12 | 0301574 | |
| IN 40-S-M8 | 0301474 | |
| INK 40-S | 0301555 | |

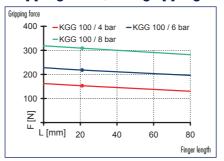
Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.



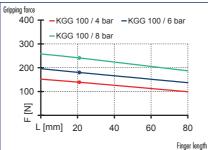
Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



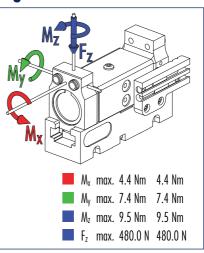
Gripping force, I.D. gripping



Gripping force, O.D. gripping



Finger load



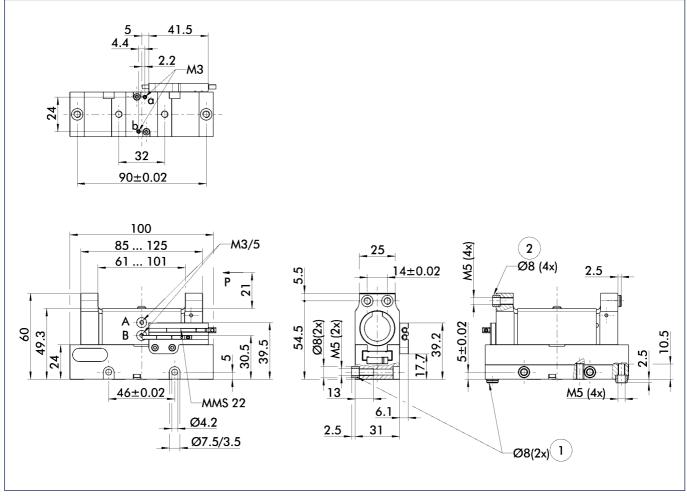
Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

| Description | | KGG 100-40 | KGG 100-80 | |
|-----------------------------------|--------------------|------------|------------|--|
| | ID | 0303065 | 0303066 | |
| Stroke per finger | [mm] | 20.0 | 40.0 | |
| Closing force | [N] | 175.0 | 175.0 | |
| Opening force | [N] | 220.0 | 220.0 | |
| Weight | [kg] | 0.37 | 0.5 | |
| Recommended workpiece weight | [kg] | 0.9 | 0.9 | |
| Air consumption per double stroke | [cm ³] | 22.5 | 45.0 | |
| Nominal pressure | [bar] | 6.0 | 6.0 | |
| Minimum pressure | [bar] | 2.0 | 2.0 | |
| Maximum pressure | [bar] | 8.0 | 8.0 | |
| Closing time | [S] | 0.09 | 0.15 | |
| Opening time | [S] | 0.07 | 0.14 | |
| Max. permitted finger length | [mm] | 80.0 | 80.0 | |
| Max. permitted weight per finger | [kg] | 0.3 | 0.3 | |
| IP class | | 40 | 40 | |
| Min. ambient temperature | [° (] | -10.0 | -10.0 | |
| Max. ambient temperature | [° (] | 90.0 | 90.0 | |
| Repeat accuracy | [mm] | 0.02 | 0.02 | |



Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

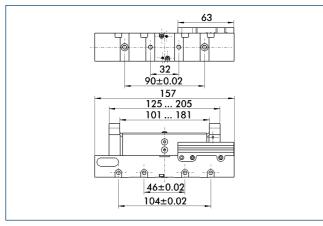
Main views



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(i) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

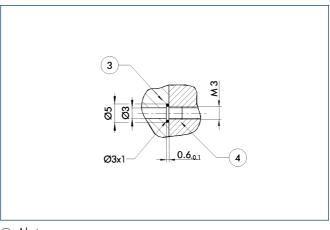
KGG 100-80 (double stroke)



The KGG 100-80 is a version with double stroke length

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- (1) Gripper connection
- (2) Finger connection

Hose-free direct connection



3 Adapter

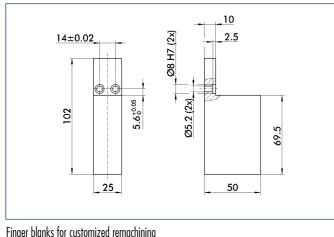
 $\bar{\textbf{4}} \quad \text{Gripper}$

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.



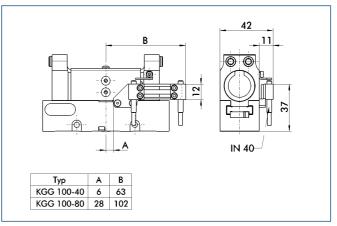
Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

Finger blanks



| Description | Materia | Scope of delivery | ID |
|-------------|----------|-------------------|---------|
| RB 100 | Aluminum | 2 | 0303090 |

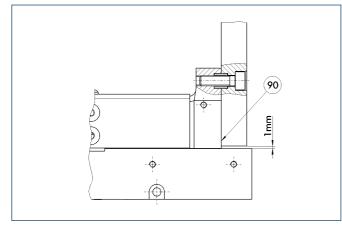
Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

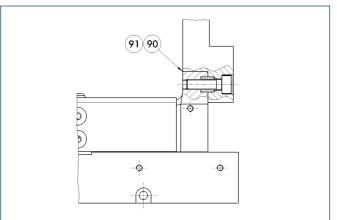
| Description | ID |
|--------------------------------|---------|
| AS-KGG 100-40 | 0303082 |
| AS-KGG 80-60 / 100-80 / 140-60 | 0303084 |

Jaw design O.D. gripping



90 Support top jaws at the base jaw

Jaw design I.D. gripping

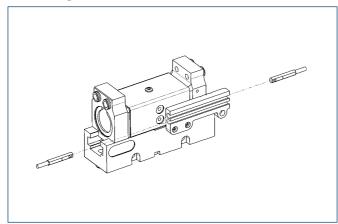


90 Support top jaws at the base jaw

(91) For dimensions of steps at the top jaw see drawings of finger blanks



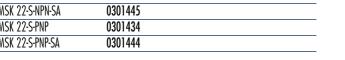
Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

| Description | ID | Recommended product |
|--------------------|---------|---------------------|
| MMS 22-S-M5-NPN | 0301439 | - |
| MMS 22-S-M5-NPN-SA | 0301449 | |
| MMS 22-S-M5-PNP | 0301438 | |
| MMS 22-S-M5-PNP-SA | 0301448 | |
| MMS 22-S-M8-NPN | 0301433 | |
| MMS 22-S-M8-NPN-SA | 0301443 | |
| MMS 22-S-M8-PNP | 0301432 | • |
| MMS 22-S-M8-PNP-SA | 0301442 | |
| MMSK 22-S-NPN | 0301435 | |
| MMSK 22-S-NPN-SA | 0301445 | |
| MMSK 22-S-PNP | 0301434 | |
| MMSK 22-S-PNP-SA | 0301444 | |
| | | |

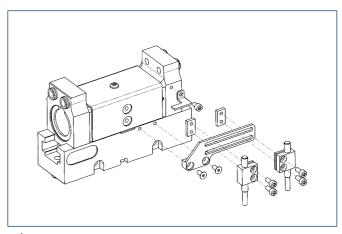


(1) Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

Extensioncables for proximity switches/magnetic switches

| | | • |
|--------------------------|---------|---|
| Description | ID | |
| KA BG05-L 3P-0300 | 0301652 | |
| KA BGO8-L 3P-0300-PNP | 0301622 | |
| KA BW05-L 3P-0300 | 0301650 | |
| KA BWO8-L 3P-0300-NPN | 0301602 | |
| KA BWO8-L 3P-0300-PNP | 0301594 | |
| KA BWO8-L 3P-0500-NPN | 9641116 | |
| KA BW08-L 3P-0500-PNP | 0301502 | |
| KA BW12-L 3P-0300-PNP | 0301503 | |
| KA BW12-L 3P-0500-PNP | 0301507 | |
| KV BW08-SG08 3P-0030-PNP | 0301495 | |
| KV BW08-SG08 3P-0100-PNP | 0301496 | |
| KV BW08-SG08 3P-0200-PNP | 0301497 | |
| KV BW12-SG12 3P-0030-PNP | 0301595 | |
| KV BW12-SG12 3P-0100-PNP | 0301596 | |
| KV BW12-SG12 3P-0200-PNP | 0301597 | |
| | | |

① Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



End position monitoring:

Inductive proximity switches, mounted with mounting kit Doccrint

| Description | U | |
|--------------------------------|---------|--|
| AS-KGG 100-40 | 0303082 | |
| AS-KGG 80-60 / 100-80 / 140-60 | 0303084 | |
| IN 40-S-M12 | 0301574 | |
| IN 40-S-M8 | 0301474 | |
| INK 40-S | 0301555 | |

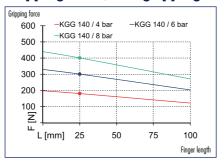
(1) Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.



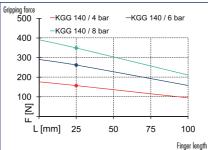
Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



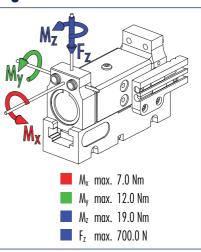
Gripping force, I.D. gripping



Gripping force, O.D. gripping



Finger load



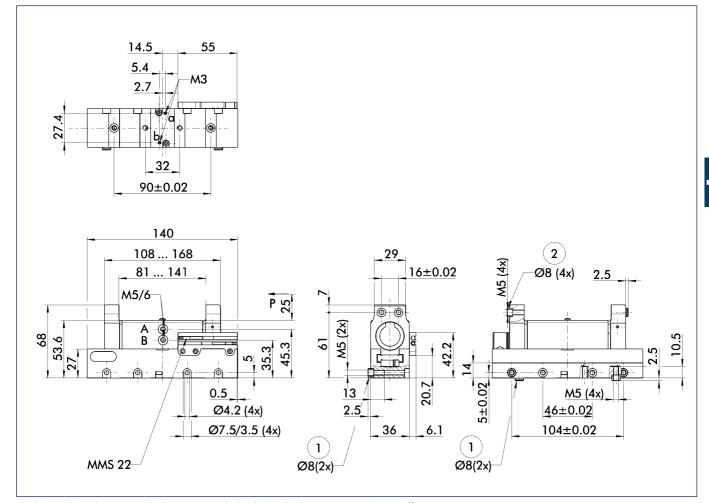
Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

| Description | | KGG 140-60 | |
|-----------------------------------|--------------------|------------|--|
| | ID | 0303070 | |
| Stroke per finger | [mm] | 30.0 | |
| Closing force | [N] | 260.0 | |
| Opening force | [N] | 300.0 | |
| Weight | [kg] | 0.77 | |
| Recommended workpiece weight | [kg] | 1.3 | |
| Air consumption per double stroke | [cm ³] | 42.0 | |
| Nominal pressure | [bar] | 6.0 | |
| Minimum pressure | [bar] | 2.0 | |
| Maximum pressure | [bar] | 8.0 | |
| Closing time | [S] | 0.17 | |
| Opening time | [S] | 0.17 | |
| Max. permitted finger length | [mm] | 100.0 | |
| Max. permitted weight per finger | [kg] | 0.5 | |
| IP class | | 40 | |
| Min. ambient temperature | [° (] | -10.0 | |
| Max. ambient temperature | [° (] | 90.0 | |
| Repeat accuracy | [mm] | 0.02 | |



Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

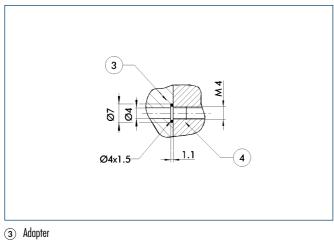
Main views



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
 - Gripper connection
 Finger connection
- (1) The SDV-P pressure maintenance valve can be used as a gripping force safety device (see "Accessories" catalog section).

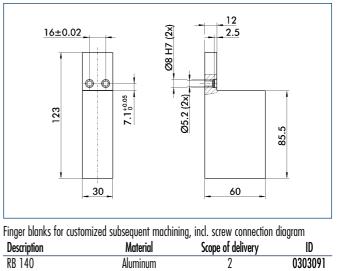
Hose-free direct connection



(4) Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

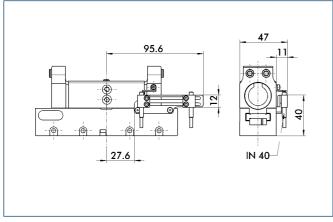
Finger blanks





Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

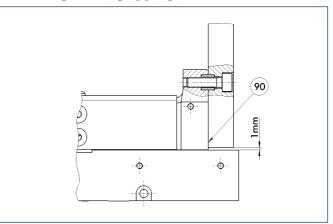
Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

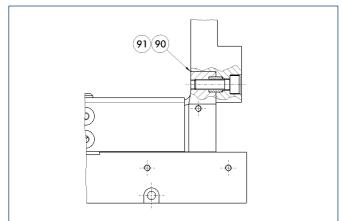
| Description | ID |
|--------------------------------|---------|
| AS-KGG 80-60 / 100-80 / 140-60 | 0303084 |

Jaw design O.D. gripping



90 Support top jaws at the base jaw

Jaw design I.D. gripping



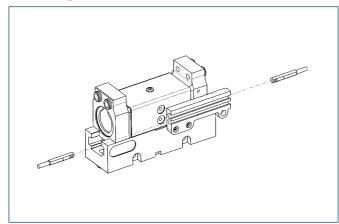
90 Support top jaws at the base jaw

(91) For dimensions of steps at the top jaw see drawings of finger blanks

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.



Sensor system



End position monitoring:

Electronic magnetic switches, for mounting in C-slot

| Description | ID | Recommended product | |
|--------------------|---------|---------------------|--|
| MMS 22-S-M5-NPN | 0301439 | | |
| MMS 22-S-M5-NPN-SA | 0301449 | | |
| MMS 22-S-M5-PNP | 0301438 | | |
| MMS 22-S-M5-PNP-SA | 0301448 | | |
| MMS 22-S-M8-NPN | 0301433 | | |
| MMS 22-S-M8-NPN-SA | 0301443 | | |
| MMS 22-S-M8-PNP | 0301432 | • | |
| MMS 22-S-M8-PNP-SA | 0301442 | | |
| MMSK 22-S-NPN | 0301435 | | |
| MMSK 22-S-NPN-SA | 0301445 | | |
| MMSK 22-S-PNP | 0301434 | | |
| MMSK 22-S-PNP-SA | 0301444 | | |

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

Extension cables for proximity switches/magnetic switches

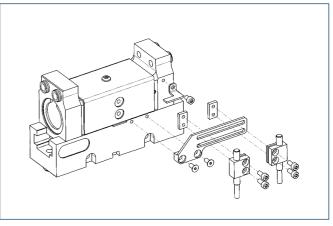
| ID |
|---------|
| 0301652 |
| 0301622 |
| 0301650 |
| 0301602 |
| 0301594 |
| 9641116 |
| 0301502 |
| 0301503 |
| 0301507 |
| 0301495 |
| 0301496 |
| 0301497 |
| 0301595 |
| 0301596 |
| 0301597 |
| |

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.







End position monitoring:

Inductive proximity switches, mounted with mounting kit Description ID

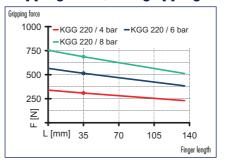
| AS-KGG 80-60 / 100-80 / 140-60 | 0303084 |
|--------------------------------|---------|
| IN 40-S-M12 | 0301574 |
| IN 40-S-M8 | 0301474 |
| INK 40-S | 0301555 |

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

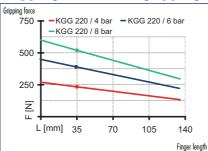
Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



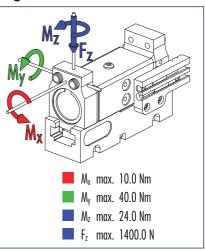
Gripping force, I.D. gripping



Gripping force, O.D. gripping



Finger load



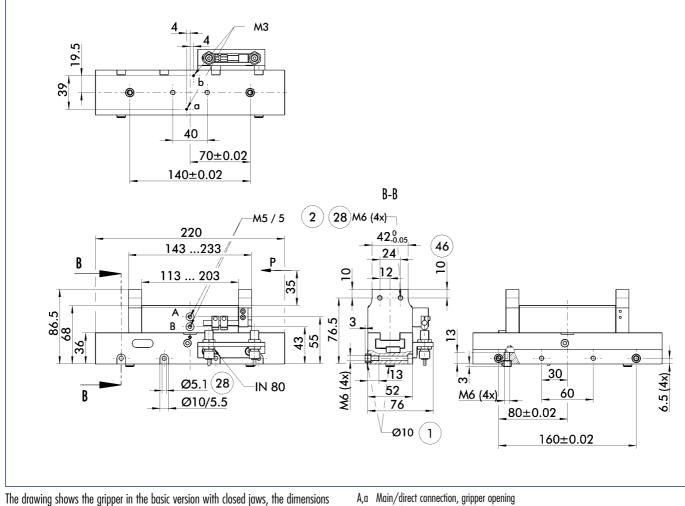
Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

| Description | | KGG 220 | |
|-----------------------------------|--------------------|---------|--|
| · · · · | ID | 0340312 | |
| Stroke per finger | [mm] | 45.0 | |
| Closing force | [N] | 390.0 | |
| Opening force | [N] | 515.0 | |
| Weight | [kg] | 2.0 | |
| Recommended workpiece weight | [kg] | 1.95 | |
| Air consumption per double stroke | [cm ³] | 98.0 | |
| Nominal pressure | [bar] | 6.0 | |
| Minimum pressure | [bar] | 2.5 | |
| Maximum pressure | [bar] | 8.0 | |
| Closing time | [S] | 0.25 | |
| Opening time | [S] | 0.25 | |
| Max. permitted finger length | [mm] | 130.0 | |
| Max. permitted weight per finger | [kg] | 1.0 | |
| IP class | | 30 | |
| Min. ambient temperature | [° (] | -10.0 | |
| Max. ambient temperature | [° (] | 90.0 | |
| Repeat accuracy | [mm] | 0.05 | |



Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

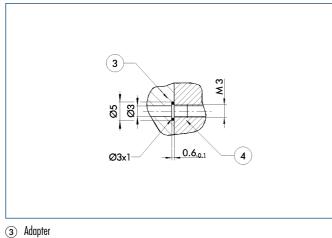
Main views



do not include the options described below.

- (1) The SDV-P pressure maintenance valve can be used as a gripping force safety device (see "Accessories" catalog section).
- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- Gripper connection
 Finger connection
- (28) Through-bore
- (46) Fitting length

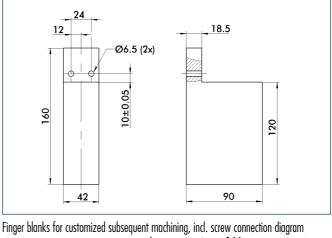
Hose-free direct connection



(4) Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

Finger blanks

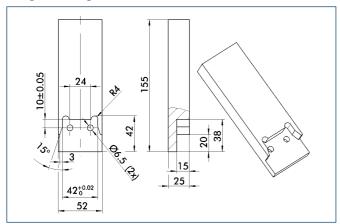


| Description | Material | Scope of delivery | ID |
|-------------|----------|-------------------|---------|
| RB 220 | Aluminum | 2 | 0300286 |



Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

Finger design

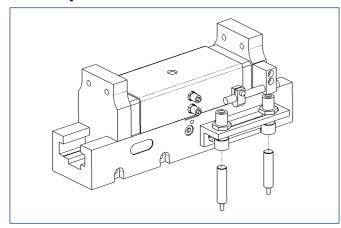


Suggested connection dimensions for gripper fingers

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

Sensor system



End position monitoring:

| Inductive proximity switches, for direct mounting | | | |
|---|---------|---------------------|--|
| Description | ID | Recommended product | |
| IN 80-S-M12 | 0301578 | | |
| IN 80-S-M8 | 0301478 | • | |
| INK 80-S | 0301550 | | |

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

Extension cables for proximity switches/magnetic switches

| EXIGNISION CODIOS TOT PLOXIM | i y sunchos, inag | |
|------------------------------|-------------------|--|
| Description | ID | |
| KA BGO8-L 3P-0300-PNP | 0301622 | |
| KA BWO8-L 3P-0300-PNP | 0301594 | |
| KA BWO8-L 3P-0500-PNP | 0301502 | |
| KA BW12-L 3P-0300-PNP | 0301503 | |
| KA BW12-L 3P-0500-PNP | 0301507 | |
| KV BW08-SG08 3P-0030-PNP | 0301495 | |
| KV BW08-SG08 3P-0100-PNP | 0301496 | |
| KV BW08-SG08 3P-0200-PNP | 0301497 | |
| KV BW12-SG12 3P-0030-PNP | 0301595 | |
| KV BW12-SG12 3P-0100-PNP | 0301596 | |
| KV BW12-SG12 3P-0200-PNP | 0301597 | |
| | | |

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

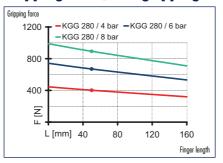
You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.



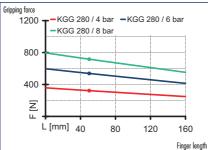
Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



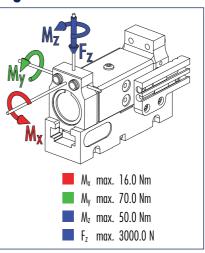
Gripping force, I.D. gripping



Gripping force, O.D. gripping



Finger load



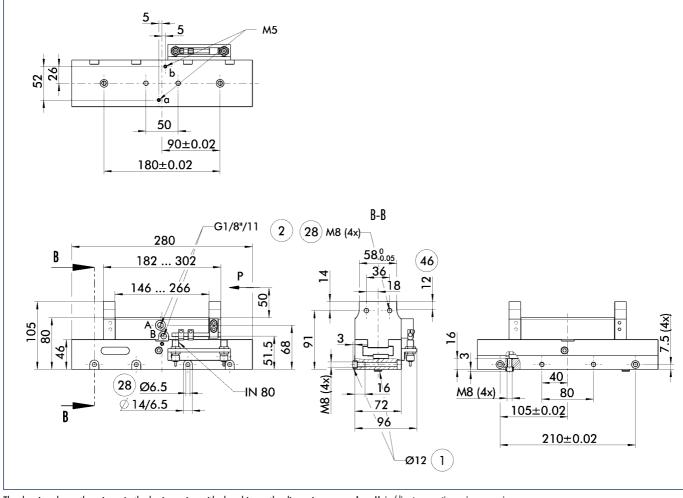
Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

| Description | | KGG 280 | |
|-----------------------------------|--------------------|---------|--|
| | ID | 0340313 | |
| Stroke per finger | [mm] | 60.0 | |
| Closing force | [N] | 540.0 | |
| Opening force | [N] | 670.0 | |
| Weight | [kg] | 4.2 | |
| Recommended workpiece weight | [kg] | 2.7 | |
| Air consumption per double stroke | [cm ³] | 170.0 | |
| Nominal pressure | [bar] | 6.0 | |
| Minimum pressure | [bar] | 2.5 | |
| Maximum pressure | [bar] | 8.0 | |
| Closing time | [S] | 0.29 | |
| Opening time | [S] | 0.25 | |
| Max. permitted finger length | [mm] | 160.0 | |
| Max. permitted weight per finger | [kg] | 2.0 | |
| IP class | | 30 | |
| Min. ambient temperature | [° (] | -10.0 | |
| Max. ambient temperature | [° (] | 90.0 | |
| Repeat accuracy | [mm] | 0.1 | |



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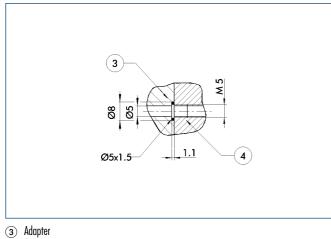
Main views



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- (1) The SDV-P pressure maintenance valve can be used as a gripping force safety device (see "Accessories" catalog section).
- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- Gripper connection
 Finger connection
- (28) Through-bore
- (46) Fitting length

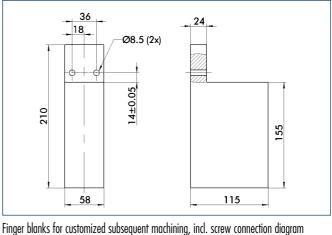
Hose-free direct connection



⁽⁴⁾ Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

Finger blanks

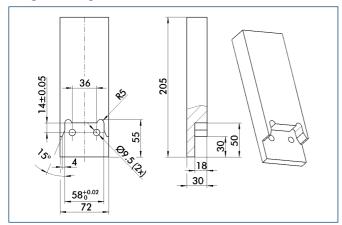


| Thiger blunks to | ii cusioiniizeu sousequein mucininiiy, | IIICI. SCIEW COIMECHON | uluyiuiii |
|------------------|--|------------------------|-----------|
| Description | Material | Scope of delivery | ID |
| RB 280 | Aluminum | 2 | 0300287 |



Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

Finger design

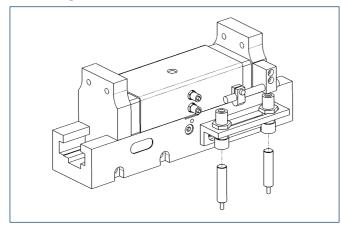


Suggested connection dimensions for gripper fingers

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

Sensor system



End position monitoring:

| Inductive proximity switches, for direct mounting | | | |
|---|---------|---------------------|--|
| Description | ID | Recommended product | |
| IN 80-S-M12 | 0301578 | - | |
| IN 80-S-M8 | 0301478 | • | |
| INK 80-S | 0301550 | | |

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

Extension cables for proximity switches/magnetic switches

| Extension cubies for proximity switches/ magnetic switches | | |
|--|--|--|
| ID | | |
| 0301622 | | |
| 0301594 | | |
| 0301502 | | |
| 0301503 | | |
| 0301507 | | |
| 0301495 | | |
| 0301496 | | |
| 0301497 | | |
| 0301595 | | |
| 0301596 | | |
| 0301597 | | |
| | ID 0301622 0301594 0301502 0301503 0301507 0301495 0301495 0301497 0301595 0301596 | |

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

