# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



Sizes 60...280



Weight 0.085 kg .. 4.2 kg



**Gripping force** 45 N .. 540 N

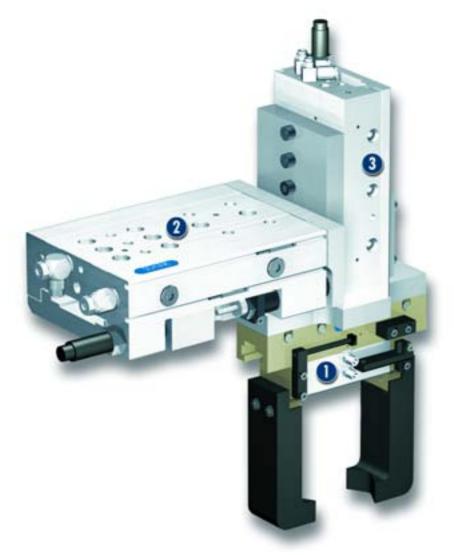


Stroke per finger 10 mm .. 60 mm



Workpiece weight 0.3 kg .. 2.7 kg

## **Application example**



Ejection unit for small components, which require an especially long gripper stroke due to their great variation in size



KGG 140 2-Finger Parallel Gripper with workpiece-specific fingers



FST-S 25-40 Mini-slide for horizontal movement

3





## **Gripper for Small Components**

Narrow 2-finger parallel gripper with long stroke

### Area of application

for universal use in clean environments with light to medium workpiece weights and a long stroke range

#### Your advantages and benefits

**Robust T-slot guide** for high maximum moments

**Pneumatic 2-piston drive design** for direct power transmission and high efficiency

**Rack and pinion principle** for centric clamping, even with long strokes

Mounting from two sides in three screw directions for universal and flexible gripper assembly

Air supply via hose-free direct connection or screw connections

for the flexible supply of compressed air in all automation systems



### General information on the series

Working principle Directly driven base jaws, synchronized by rack and pinion

Housing material Aluminum alloy, hard-anodized

Base jaw material Aluminum alloy, hard-anodized

#### Actuation

Pneumatic, with filtered compressed air (10  $\mu$ m): Dry, lubricated or non-lubricated Pressure medium: Requirements on quality of the compressed air according to DIN ISO 8573-1: 6 4 4.

#### Warranty

24 months

Scope of delivery Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly and operating manual with manufacturer's declaration

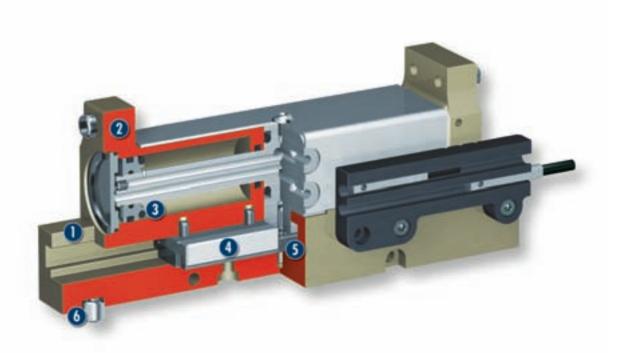
#### Maintenance of gripping force

possible with SDV-P pressure maintenance valve



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## Sectional diagram



#### 1 Housing

weight-reduced through the use of a hardanodized, high-strength aluminum alloy



Base jaws

for the connection of workpiece-specific gripper fingers



Drive Pneumatic 2-piston system



Guidance high maximum moments through robust T-slot guide



**Kinematics** 

rack and pinion principle for centric gripping, even with long strokes



Centering and mounting possibilities for assembly of the gripper to a base area and at the long side

## **Function description**

The base jaws, arranged in a line, are introduced with compressed air directly by the fixed piston, which causes them to open and close. The base jaws are synchronized by the internal rack and pinion arrangement.

## **Options and special information**

Please note that the mass moment of inertia of the gripper fingers must be kept to a minimum in the case of long-stroke grippers.



# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

SCHUNK

#### Accessories

Accessories from SCHUNK – the suitable supplement for maximum functionality, reliability and performance of all automation modules.

# HM carbide clamping inserts



Quentes plastic inserts





IN inductive proximity switches



**KV/KA** sensor cables







FPS flexible position sensor



HKI gripper pads



#### SDV-P pressure maintenance valves



**Finger blanks** 



For the exact size of the required accessories, availability of this size and the designation and ID, please refer to the additional views at the end of the size in question. You will find more detailed information on our accessory range in the "Accessories" catalog section.

### General information on the series

#### **Gripping force**

is the arithmetic total of the gripping force applied to each base jaw at distance P (see illustration), measured from the upper edge of the gripper.

#### **Finger length**

is measured from the upper edge of the gripper housing in the direction of the main axis.

#### **Repeat accuracy**

is defined as the spread of the limit position after 100 consecutive strokes.

#### Workpiece weight

The recommended workpiece weight is calculated for a force-type connection with a coefficient of friction of 0.1 and a safety factor of 2 against slippage of the workpiece on acceleration due to gravity g. Considerably heavier workpiece weights are permitted with form-fit gripping.

#### **Closing and opening times**

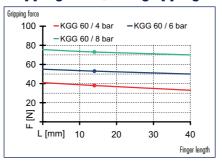
Closing and opening times are purely the times that the base jaws or fingers are in motion. Valve switching times, hose filling times or PLC reaction times are not included in the above times and must be taken into consideration when determining cycle times.



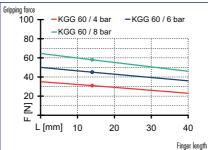
# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



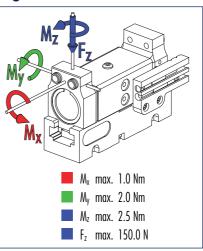
## Gripping force, I.D. gripping



## Gripping force, O.D. gripping



## **Finger** load



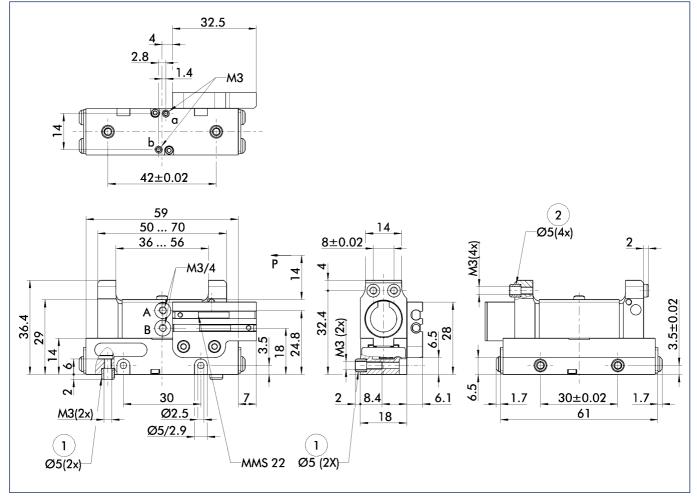
(1) Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		KGG 60-20	KGG 60-40	
	ID	0303050	0303051	
Stroke per finger	[mm]	10.0	20.0	
Closing force	[N]	45.0	45.0	
Opening force	[N]	53.0	53.0	
Weight	[kg]	0.085	0.108	
Recommended workpiece weight	[kg]	0.23	0.23	
Air consumption per double stroke	[cm <sup>3</sup> ]	3.0	6.0	
Nominal pressure	[bar]	6.0	6.0	
Minimum pressure	[bar]	2.0	2.0	
Maximum pressure	[bar]	8.0	8.0	
Closing time	[5]	0.03	0.04	
Opening time	[S]	0.03	0.04	
Max. permitted finger length	[mm]	42.0	42.0	
Max. permitted weight per finger	[kg]	0.04	0.04	
IP class		40	40	
Min. ambient temperature	[° <b>(</b> ]	-10.0	-10.0	
Max. ambient temperature	[° <b>(</b> ]	90.0	90.0	
Repeat accuracy	[mm]	0.02	0.02	



## Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

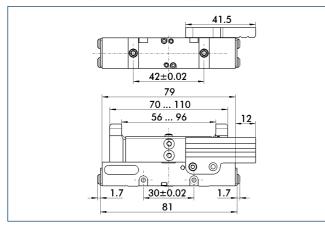
## **Main views**



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(1) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

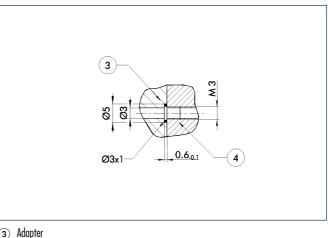
#### KGG 60-40 (double stroke)



The KGG 60-40 is a version with double stroke length.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- ① Gripper connection
- 2 Finger connection

## Hose-free direct connection



3

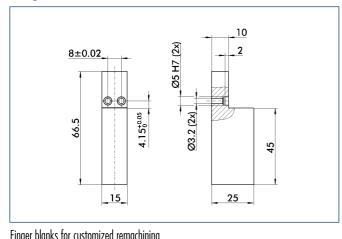
(ā) Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.



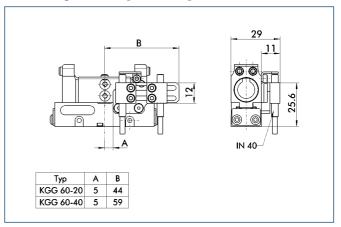
## Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

## **Finger blanks**



Description	Material	Scope of delivery	ID
RB 60	Aluminum	2	0303087

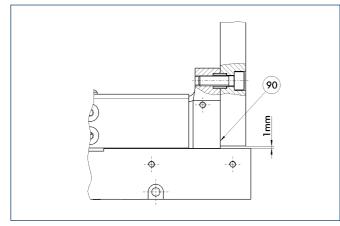
## Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

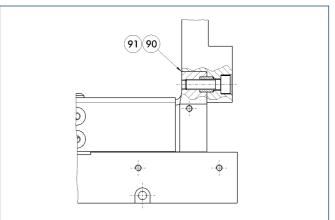
Description	ID '	,
AS-KGG 60-20 / 70-24	0303081	
AS-KGG 60-40 / 70-48	0303080	

## Jaw design O.D. gripping



90 Support top jaws at the base jaw

## Jaw design I.D. gripping

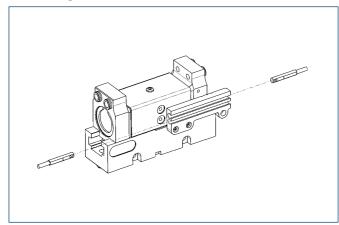


90 Support top jaws at the base jaw

(91) For dimensions of steps at the top jaw see drawings of finger blanks



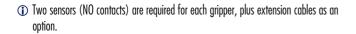
## Sensor system



#### End position monitoring:

Electronic magnetic switches, for mounting in C-slot

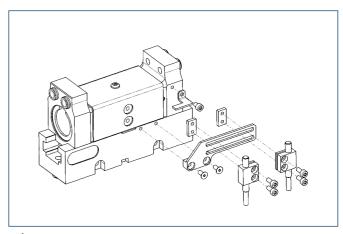
Description	ID	Recommended product	
MMS 22-S-M5-NPN	0301439	·	
MMS 22-S-M5-NPN-SA	0301449		
MMS 22-S-M5-PNP	0301438		
MMS 22-S-M5-PNP-SA	0301448		
MMS 22-S-M8-NPN	0301433		
MMS 22-S-M8-NPN-SA	0301443		
MMS 22-S-M8-PNP	0301432	•	
MMS 22-S-M8-PNP-SA	0301442		
MMSK 22-S-NPN	0301435		
MMSK 22-S-NPN-SA	0301445		
MMSK 22-S-PNP	0301434		
MMSK 22-S-PNP-SA	0301444		



#### Extension cables for proximity switches/magnetic switches

Description	ID	
KA BG05-L 3P-0300	0301652	
KA BGO8-L 3P-0300-PNP	0301622	
KA BW05-L 3P-0300	0301650	
KA BWO8-L 3P-0300-NPN	0301602	
KA BWO8-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-NPN	9641116	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



#### End position monitoring:

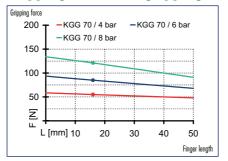
Inductive proximity switches, mounted with mounting kit			
Description	ID		
AS-KGG 60-20 / 70-24	0303081		
AS-KGG 60-40 / 70-48	0303080		
IN 40-S-M12	0301574		
IN 40-S-M8	0301474		
INK 40-S	0301555		

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

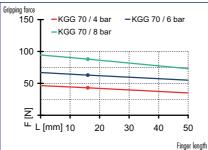
# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



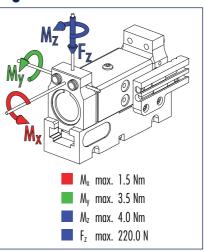
## Gripping force, I.D. gripping



## Gripping force, O.D. gripping



## **Finger** load



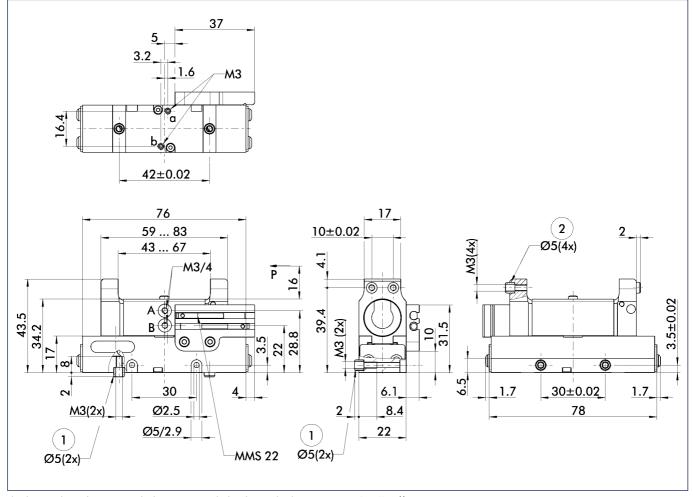
① Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		KGG 70-24	KGG 70-48	
	ID	0303055	0303056	
Stroke per finger	[mm]	12.0	24.0	
Closing force	[N]	62.0	62.0	
Opening force	[N]	85.0	85.0	
Weight	[kg]	0.15	0.192	
Recommended workpiece weight	[kg]	0.32	0.32	
Air consumption per double stroke	[cm <sup>3</sup> ]	5.0	10.0	
Nominal pressure	[bar]	6.0	6.0	
Minimum pressure	[bar]	2.0	2.0	
Maximum pressure	[bar]	8.0	8.0	
Closing time	[5]	0.04	0.05	
Opening time	[5]	0.04	0.05	
Max. permitted finger length	[mm]	50.0	50.0	
Max. permitted weight per finger	[kg]	0.06	0.06	
IP class		40	40	
Min. ambient temperature	[° <b>(</b> ]	-10.0	-10.0	
Max. ambient temperature	[° <b>(</b> ]	90.0	90.0	
Repeat accuracy	[mm]	0.02	0.02	



## Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

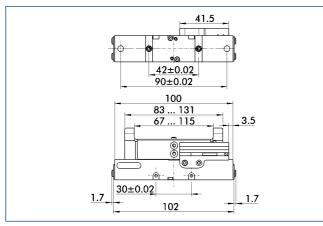
## **Main views**



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(1) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

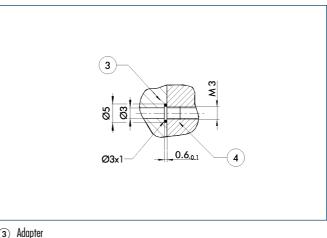
#### KGG 70-48 (double stroke)



The KGG 70-48 is a version with double stroke length.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- ① Gripper connection
- 2 Finger connection

#### Hose-free direct connection



3

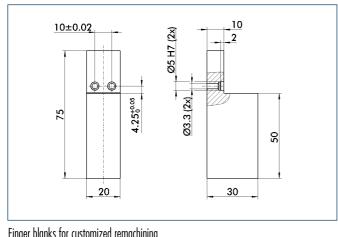
(ā) Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.



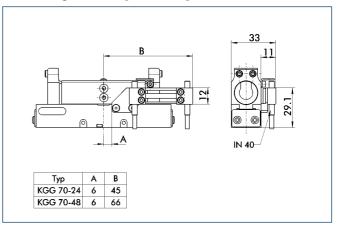
# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

## **Finger blanks**



Description	Material	Scope of delivery	ID
RB 70	Aluminum	2	0303088

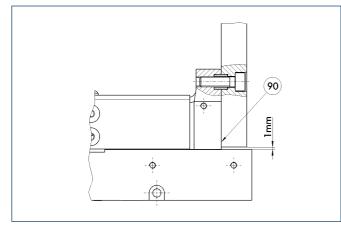
## Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

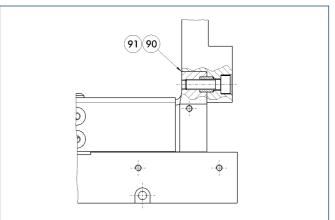
Description	ID .	1
AS-KGG 60-20 / 70-24	0303081	
AS-KGG 60-40 / 70-48	0303080	

## Jaw design O.D. gripping



90 Support top jaws at the base jaw

## Jaw design I.D. gripping

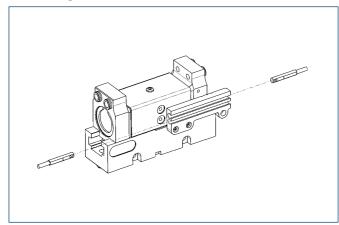


90 Support top jaws at the base jaw

(91) For dimensions of steps at the top jaw see drawings of finger blanks



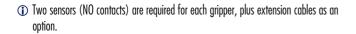
## Sensor system



#### End position monitoring:

Electronic magnetic switches, for mounting in C-slot

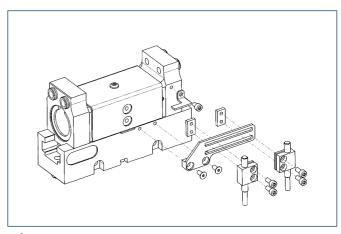
Description	ID	Recommended product	
MMS 22-S-M5-NPN	0301439		
MMS 22-S-M5-NPN-SA	0301449		
MMS 22-S-M5-PNP	0301438		
MMS 22-S-M5-PNP-SA	0301448		
MMS 22-S-M8-NPN	0301433		
MMS 22-S-M8-NPN-SA	0301443		
MMS 22-S-M8-PNP	0301432	•	
MMS 22-S-M8-PNP-SA	0301442		
MMSK 22-S-NPN	0301435		
MMSK 22-S-NPN-SA	0301445		
MMSK 22-S-PNP	0301434		
MMSK 22-S-PNP-SA	0301444		



#### Extension cables for proximity switches/magnetic switches

Description	ID	
KA BG05-L 3P-0300	0301652	
KA BGO8-L 3P-0300-PNP	0301622	
KA BW05-L 3P-0300	0301650	
KA BWO8-L 3P-0300-NPN	0301602	
KA BWO8-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-NPN	9641116	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



#### End position monitoring:

Inductive proximity switches, mounted with mounting kit			
Description	ID		
AS-KGG 60-20 / 70-24	0303081		
AS-KGG 60-40 / 70-48	0303080		
IN 40-S-M12	0301574		
IN 40-S-M8	0301474		
INK 40-S	0301555		

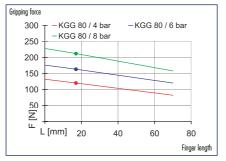
Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.



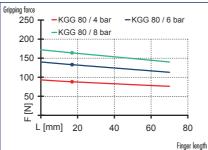
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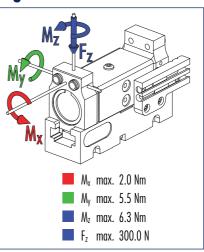
## Gripping force, I.D. gripping



## Gripping force, O.D. gripping



## **Finger** load



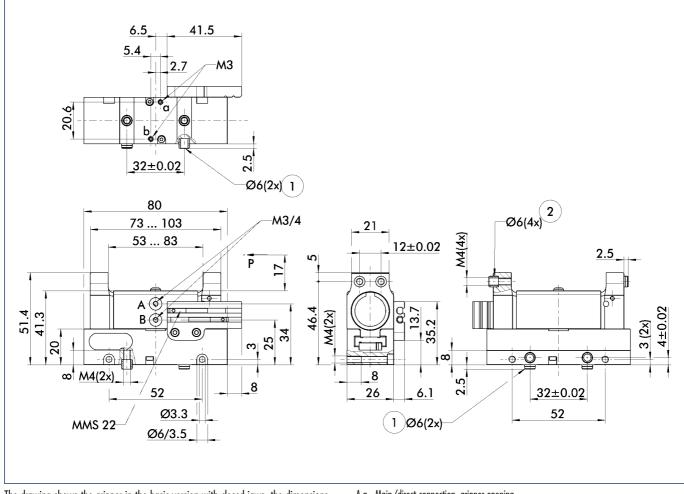
Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		KGG 80-30	KGG 80-60	
	ID	0303060	0303061	
Stroke per finger	[mm]	15.0	30.0	
Closing force	[N]	130.0	130.0	
Opening force	[N]	165.0	165.0	
Weight	[kg]	0.25	0.33	
Recommended workpiece weight	[kg]	0.66	0.66	
Air consumption per double stroke	[cm <sup>3</sup> ]	12.0	24.0	
Nominal pressure	[bar]	6.0	6.0	
Minimum pressure	[bar]	2.0	2.0	
Maximum pressure	[bar]	8.0	8.0	
Closing time	[5]	0.05	0.08	
Opening time	[5]	0.05	0.07	
Max. permitted finger length	[mm]	80.0	80.0	
Max. permitted weight per finger	[kg]	0.15	0.15	
IP class		40	40	
Min. ambient temperature	[° <b>(</b> ]	-10.0	-10.0	
Max. ambient temperature	[° <b>(</b> ]	90.0	90.0	
Repeat accuracy	[mm]	0.02	0.02	



## Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

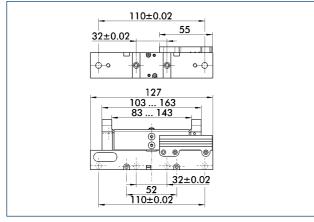
## **Main views**



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(i) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

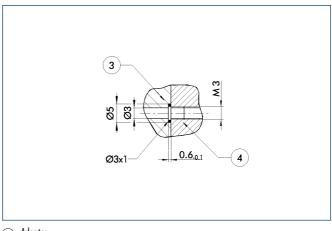
#### KGG 80-60 (double stroke)



The KGG 80-60 is a version with double stroke length.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- ① Gripper connection
- (2) Finger connection

## **Hose-free direct connection**



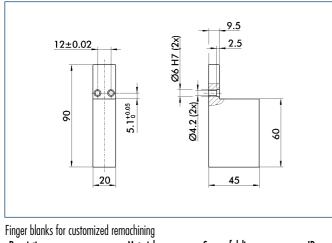
3 Adapter4 Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.



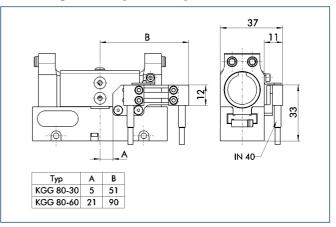
## Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

## **Finger blanks**



Description	Material	Scope of delivery	ID
RB 80	Aluminum	2	0303089

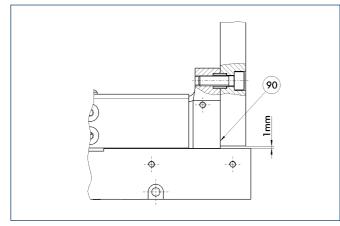
## Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

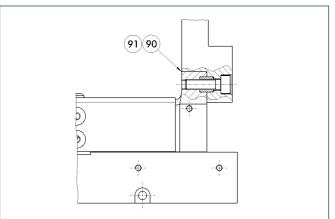
Description	ID
AS-KGG 80-30	0303083
AS-KGG 80-60 / 100-80 / 140-60	0303084

## Jaw design O.D. gripping



90 Support top jaws at the base jaw

## Jaw design I.D. gripping

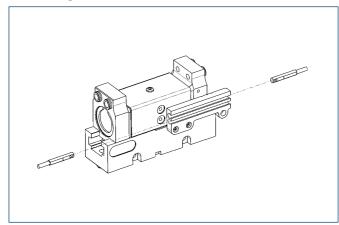


90 Support top jaws at the base jaw

(91) For dimensions of steps at the top jaw see drawings of finger blanks



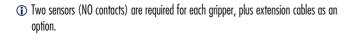
## Sensor system



#### End position monitoring:

Electronic magnetic switches, for mounting in C-slot

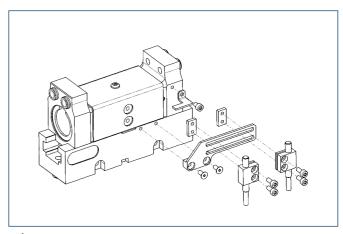
Description	ID	Recommended product
MMS 22-S-M5-NPN	0301439	-
MMS 22-S-M5-NPN-SA	0301449	
MMS 22-S-M5-PNP	0301438	
MMS 22-S-M5-PNP-SA	0301448	
MMS 22-S-M8-NPN	0301433	
MMS 22-S-M8-NPN-SA	0301443	
MMS 22-S-M8-PNP	0301432	•
MMS 22-S-M8-PNP-SA	0301442	
MMSK 22-S-NPN	0301435	
MMSK 22-S-NPN-SA	0301445	
MMSK 22-S-PNP	0301434	
MMSK 22-S-PNP-SA	0301444	



#### Extension cables for proximity switches/magnetic switches

Description	ID	•
KA BG05-L 3P-0300	0301652	
KA BGO8-L 3P-0300-PNP	0301622	
KA BW05-L 3P-0300	0301650	
KA BW08-L 3P-0300-NPN	0301602	
KA BWO8-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-NPN	9641116	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



#### End position monitoring:

Inductive proximity switches, mounted with mounting kit

Description	ĬD	
AS-KGG 80-30	0303083	
AS-KGG 80-60 / 100-80 / 140-60	0303084	
IN 40-S-M12	0301574	
IN 40-S-M8	0301474	
INK 40-S	0301555	

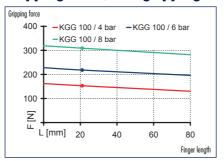
Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.



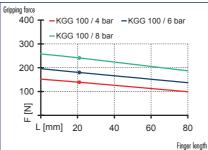
# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



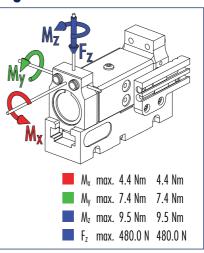
## Gripping force, I.D. gripping



## Gripping force, O.D. gripping



## **Finger** load



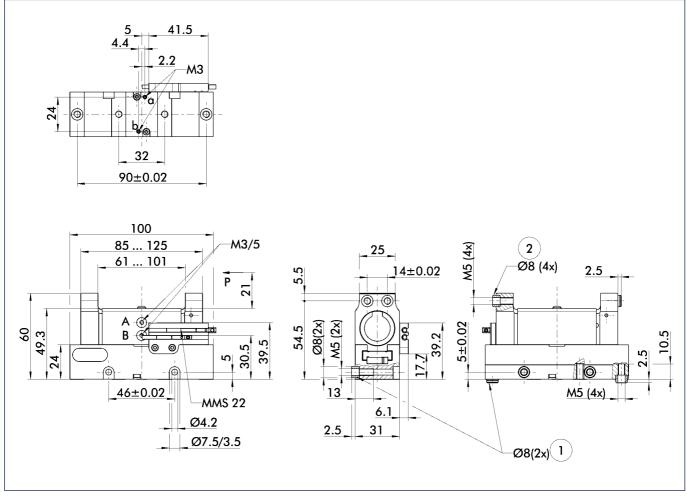
Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		KGG 100-40	KGG 100-80	
	ID	0303065	0303066	
Stroke per finger	[mm]	20.0	40.0	
Closing force	[N]	175.0	175.0	
Opening force	[N]	220.0	220.0	
Weight	[kg]	0.37	0.5	
Recommended workpiece weight	[kg]	0.9	0.9	
Air consumption per double stroke	[cm <sup>3</sup> ]	22.5	45.0	
Nominal pressure	[bar]	6.0	6.0	
Minimum pressure	[bar]	2.0	2.0	
Maximum pressure	[bar]	8.0	8.0	
Closing time	[S]	0.09	0.15	
Opening time	[S]	0.07	0.14	
Max. permitted finger length	[mm]	80.0	80.0	
Max. permitted weight per finger	[kg]	0.3	0.3	
IP class		40	40	
Min. ambient temperature	[° <b>(</b> ]	-10.0	-10.0	
Max. ambient temperature	[° <b>(</b> ]	90.0	90.0	
Repeat accuracy	[mm]	0.02	0.02	



## Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

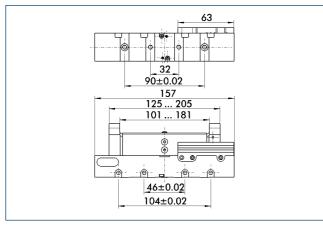
## **Main views**



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

(i) The SDV-P pressure maintenance valve can also be used (see "Accessories" catalog section) for I.D. or O.D. gripping as an alternative or in addition to the spring-loaded, mechanical gripping force safety device.

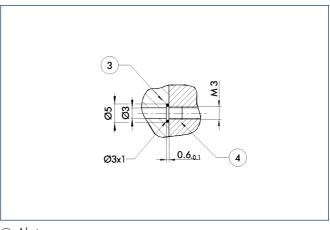
#### KGG 100-80 (double stroke)



The KGG 100-80 is a version with double stroke length

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- (1) Gripper connection
- (2) Finger connection

## **Hose-free direct connection**



3 Adapter

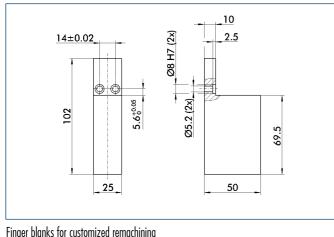
 $\bar{\textbf{4}} \quad \text{Gripper}$ 

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.



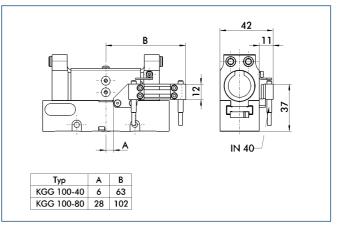
# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

## **Finger blanks**



Description	Materia	Scope of delivery	ID
RB 100	Aluminum	2	0303090

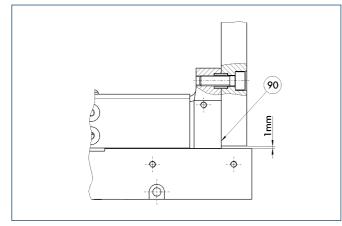
## Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

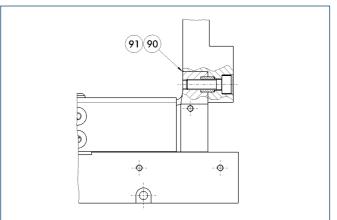
Description	ID
AS-KGG 100-40	0303082
AS-KGG 80-60 / 100-80 / 140-60	0303084

## Jaw design O.D. gripping



90 Support top jaws at the base jaw

## Jaw design I.D. gripping

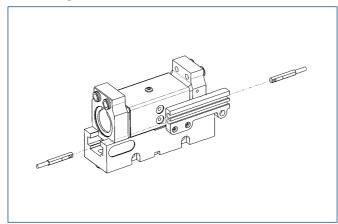


90 Support top jaws at the base jaw

(91) For dimensions of steps at the top jaw see drawings of finger blanks



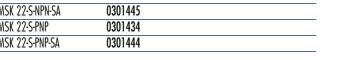
## **Sensor system**



#### End position monitoring:

Electronic magnetic switches, for mounting in C-slot

Description	ID	Recommended product
MMS 22-S-M5-NPN	0301439	-
MMS 22-S-M5-NPN-SA	0301449	
MMS 22-S-M5-PNP	0301438	
MMS 22-S-M5-PNP-SA	0301448	
MMS 22-S-M8-NPN	0301433	
MMS 22-S-M8-NPN-SA	0301443	
MMS 22-S-M8-PNP	0301432	•
MMS 22-S-M8-PNP-SA	0301442	
MMSK 22-S-NPN	0301435	
MMSK 22-S-NPN-SA	0301445	
MMSK 22-S-PNP	0301434	
MMSK 22-S-PNP-SA	0301444	

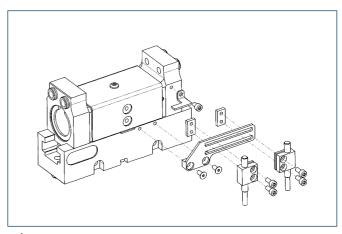


(1) Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

#### Extensioncables for proximity switches/magnetic switches

		•
Description	ID	
KA BG05-L 3P-0300	0301652	
KA BGO8-L 3P-0300-PNP	0301622	
KA BW05-L 3P-0300	0301650	
KA BWO8-L 3P-0300-NPN	0301602	
KA BWO8-L 3P-0300-PNP	0301594	
KA BWO8-L 3P-0500-NPN	9641116	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

① Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.



#### End position monitoring:

Inductive proximity switches, mounted with mounting kit Doccrint

Description	U	
AS-KGG 100-40	0303082	
AS-KGG 80-60 / 100-80 / 140-60	0303084	
IN 40-S-M12	0301574	
IN 40-S-M8	0301474	
INK 40-S	0301555	

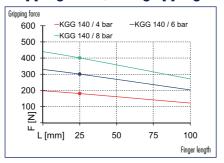
(1) Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.



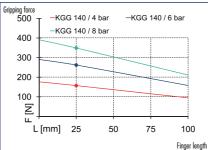
# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



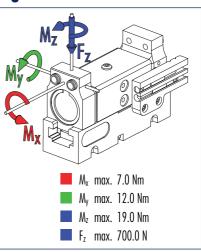
## Gripping force, I.D. gripping



## Gripping force, O.D. gripping



## **Finger load**



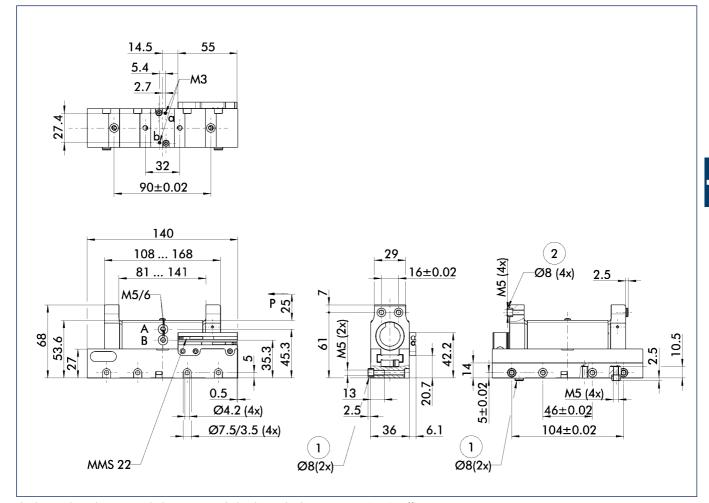
Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		KGG 140-60	
	ID	0303070	
Stroke per finger	[mm]	30.0	
Closing force	[N]	260.0	
Opening force	[N]	300.0	
Weight	[kg]	0.77	
Recommended workpiece weight	[kg]	1.3	
Air consumption per double stroke	[cm <sup>3</sup> ]	42.0	
Nominal pressure	[bar]	6.0	
Minimum pressure	[bar]	2.0	
Maximum pressure	[bar]	8.0	
Closing time	[S]	0.17	
Opening time	[S]	0.17	
Max. permitted finger length	[mm]	100.0	
Max. permitted weight per finger	[kg]	0.5	
IP class		40	
Min. ambient temperature	[° <b>(</b> ]	-10.0	
Max. ambient temperature	[° <b>(</b> ]	90.0	
Repeat accuracy	[mm]	0.02	



## Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

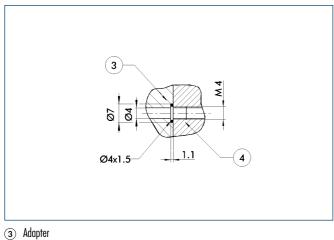
## **Main views**



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
  - Gripper connection
    Finger connection
- (1) The SDV-P pressure maintenance valve can be used as a gripping force safety device (see "Accessories" catalog section).

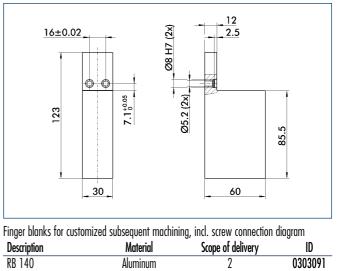
#### Hose-free direct connection



(4) Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

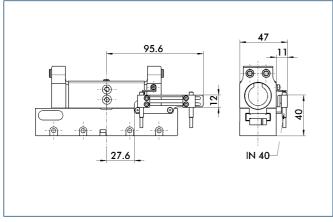
### **Finger blanks**





# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

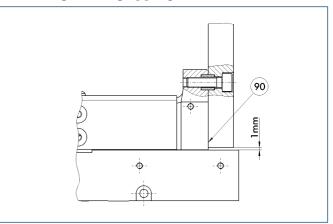
## Mounting kit for proximity switch



The mounting kit consists of brackets, switch cams and the associated mounting materials. The proximity switches must be ordered separately.

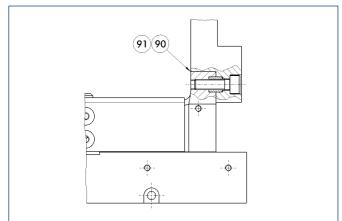
Description	ID
AS-KGG 80-60 / 100-80 / 140-60	0303084

## Jaw design O.D. gripping



90 Support top jaws at the base jaw

## Jaw design I.D. gripping



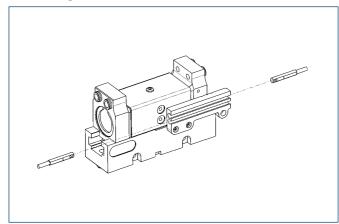
90 Support top jaws at the base jaw

(91) For dimensions of steps at the top jaw see drawings of finger blanks

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.



#### Sensor system



#### End position monitoring:

Electronic magnetic switches, for mounting in C-slot

Description	ID	Recommended product	
MMS 22-S-M5-NPN	0301439		
MMS 22-S-M5-NPN-SA	0301449		
MMS 22-S-M5-PNP	0301438		
MMS 22-S-M5-PNP-SA	0301448		
MMS 22-S-M8-NPN	0301433		
MMS 22-S-M8-NPN-SA	0301443		
MMS 22-S-M8-PNP	0301432	•	
MMS 22-S-M8-PNP-SA	0301442		
MMSK 22-S-NPN	0301435		
MMSK 22-S-NPN-SA	0301445		
MMSK 22-S-PNP	0301434		
MMSK 22-S-PNP-SA	0301444		

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

#### Extension cables for proximity switches/magnetic switches

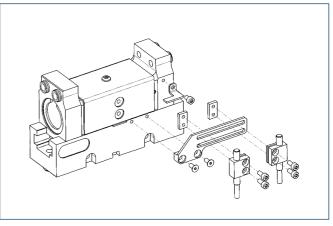
ID
0301652
0301622
0301650
0301602
0301594
9641116
0301502
0301503
0301507
0301495
0301496
0301497
0301595
0301596
0301597

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.







#### End position monitoring:

Inductive proximity switches, mounted with mounting kit Description ID

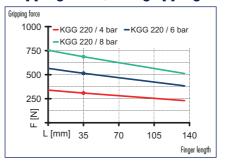
AS-KGG 80-60 / 100-80 / 140-60	0303084
IN 40-S-M12	0301574
IN 40-S-M8	0301474
INK 40-S	0301555

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

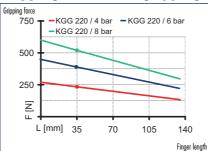
# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



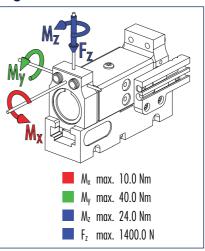
## Gripping force, I.D. gripping



## Gripping force, O.D. gripping



## **Finger** load



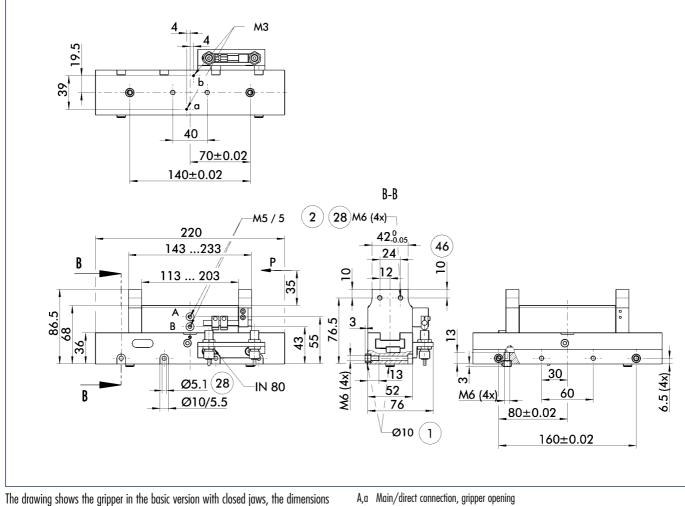
Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		KGG 220	
· · · ·	ID	0340312	
Stroke per finger	[mm]	45.0	
Closing force	[N]	390.0	
Opening force	[N]	515.0	
Weight	[kg]	2.0	
Recommended workpiece weight	[kg]	1.95	
Air consumption per double stroke	[cm <sup>3</sup> ]	98.0	
Nominal pressure	[bar]	6.0	
Minimum pressure	[bar]	2.5	
Maximum pressure	[bar]	8.0	
Closing time	[S]	0.25	
Opening time	[S]	0.25	
Max. permitted finger length	[mm]	130.0	
Max. permitted weight per finger	[kg]	1.0	
IP class		30	
Min. ambient temperature	[° <b>(</b> ]	-10.0	
Max. ambient temperature	[° <b>(</b> ]	90.0	
Repeat accuracy	[mm]	0.05	



Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

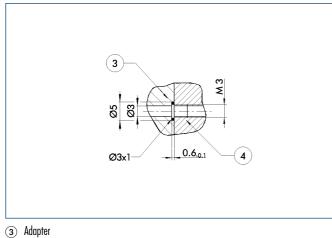
## **Main views**



do not include the options described below.

- (1) The SDV-P pressure maintenance valve can be used as a gripping force safety device (see "Accessories" catalog section).
- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- Gripper connection
  Finger connection
- (28) Through-bore
- (46) Fitting length

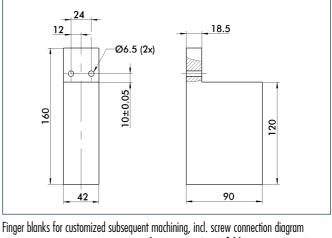
#### Hose-free direct connection



(4) Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

### **Finger blanks**

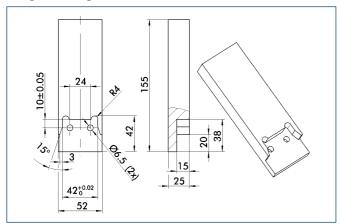


Description	Material	Scope of delivery	ID
RB 220	Aluminum	2	0300286



# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

## Finger design

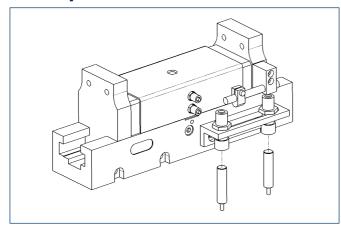


Suggested connection dimensions for gripper fingers

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

## Sensor system



#### End position monitoring:

Inductive proximity switches, for direct mounting			
Description	ID	Recommended product	
IN 80-S-M12	0301578		
IN 80-S-M8	0301478	•	
INK 80-S	0301550		

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

#### Extension cables for proximity switches/magnetic switches

EXIGNISION CODIOS TOT PLOXIM	i y sunchos, inag	
Description	ID	
KA BGO8-L 3P-0300-PNP	0301622	
KA BWO8-L 3P-0300-PNP	0301594	
KA BWO8-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

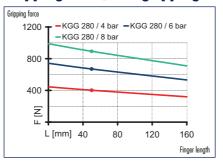
You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.



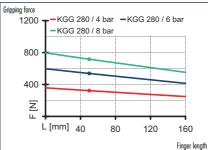
# Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components



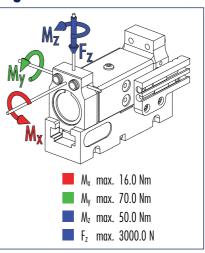
## Gripping force, I.D. gripping



## Gripping force, O.D. gripping



## **Finger** load



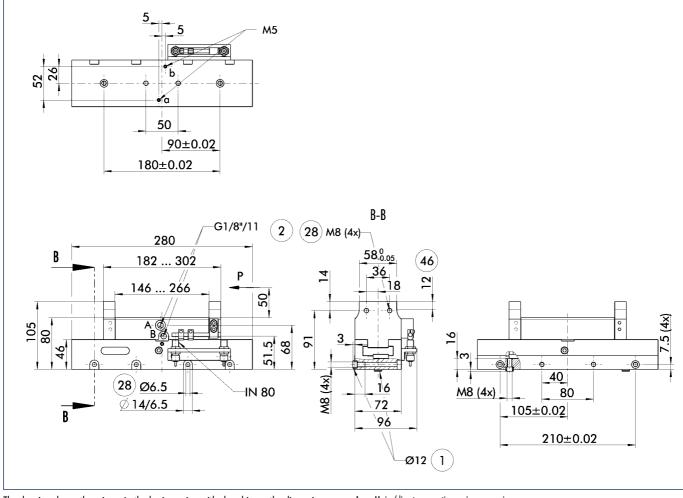
Moments and forces apply per base jaw and may occur simultaneously. My may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. Service life may reduce.

Description		KGG 280	
	ID	0340313	
Stroke per finger	[mm]	60.0	
Closing force	[N]	540.0	
Opening force	[N]	670.0	
Weight	[kg]	4.2	
Recommended workpiece weight	[kg]	2.7	
Air consumption per double stroke	[cm <sup>3</sup> ]	170.0	
Nominal pressure	[bar]	6.0	
Minimum pressure	[bar]	2.5	
Maximum pressure	[bar]	8.0	
Closing time	[S]	0.29	
Opening time	[S]	0.25	
Max. permitted finger length	[mm]	160.0	
Max. permitted weight per finger	[kg]	2.0	
IP class		30	
Min. ambient temperature	[° <b>(</b> ]	-10.0	
Max. ambient temperature	[° <b>(</b> ]	90.0	
Repeat accuracy	[mm]	0.1	



## Pneumatic • 2-Finger Parallel Gripper • Gripper for Small Components

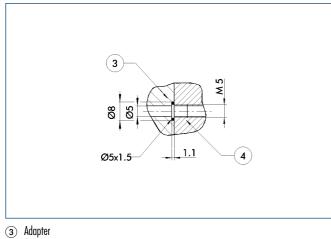
## **Main views**



The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

- (1) The SDV-P pressure maintenance valve can be used as a gripping force safety device (see "Accessories" catalog section).
- A,a Main/direct connection, gripper opening
- B,b Main/direct connection, gripper closing
- Gripper connection
  Finger connection
- (28) Through-bore
- (46) Fitting length

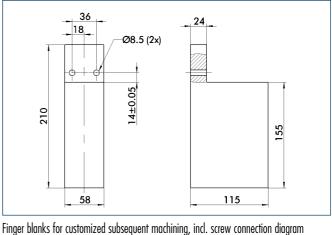
#### Hose-free direct connection



<sup>(4)</sup> Gripper

The direct connection is used for supplying compressed air to the gripper without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

## **Finger blanks**

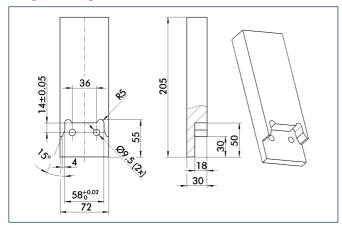


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Description	Material	Scope of delivery	ID
RB 280	Aluminum	2	0300287



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## Finger design

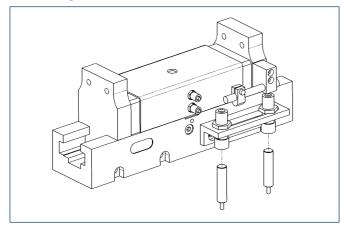


Suggested connection dimensions for gripper fingers

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

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## Sensor system



#### End position monitoring:

Inductive proximity switches, for direct mounting			
Description	ID	Recommended product	
IN 80-S-M12	0301578	-	
IN 80-S-M8	0301478	•	
INK 80-S	0301550		

Two sensors (NO contacts) are required for each gripper, plus extension cables as an option.

#### Extension cables for proximity switches/magnetic switches

Extension cubies for proximity switches/ magnetic switches		
ID		
0301622		
0301594		
0301502		
0301503		
0301507		
0301495		
0301496		
0301497		
0301595		
0301596		
0301597		
	ID 0301622 0301594 0301502 0301503 0301507 0301495 0301495 0301497 0301595 0301596	

Please note the minimum permitted bending radii for the sensor cables, which are generally 35 mm.

You can find more detailed information and individual parts of the above-mentioned accessories in the "Accessories" catalog section.

